

USNCCM-XI

11th US National Congress
on Computational Mechanics
Minneapolis
July 25-29, 2011

Identification of fracture properties for a cohesive model using digital image correlation



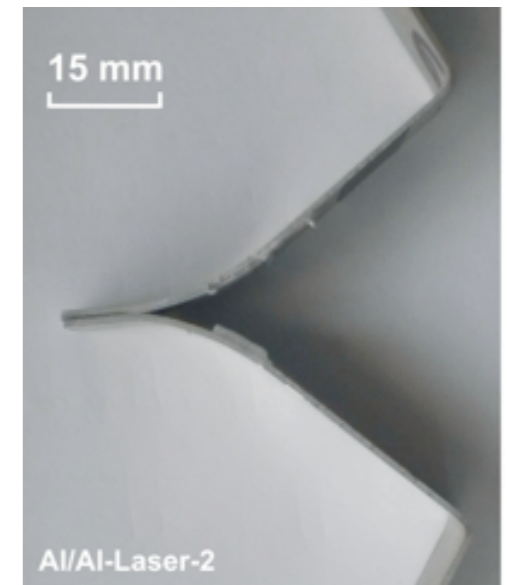
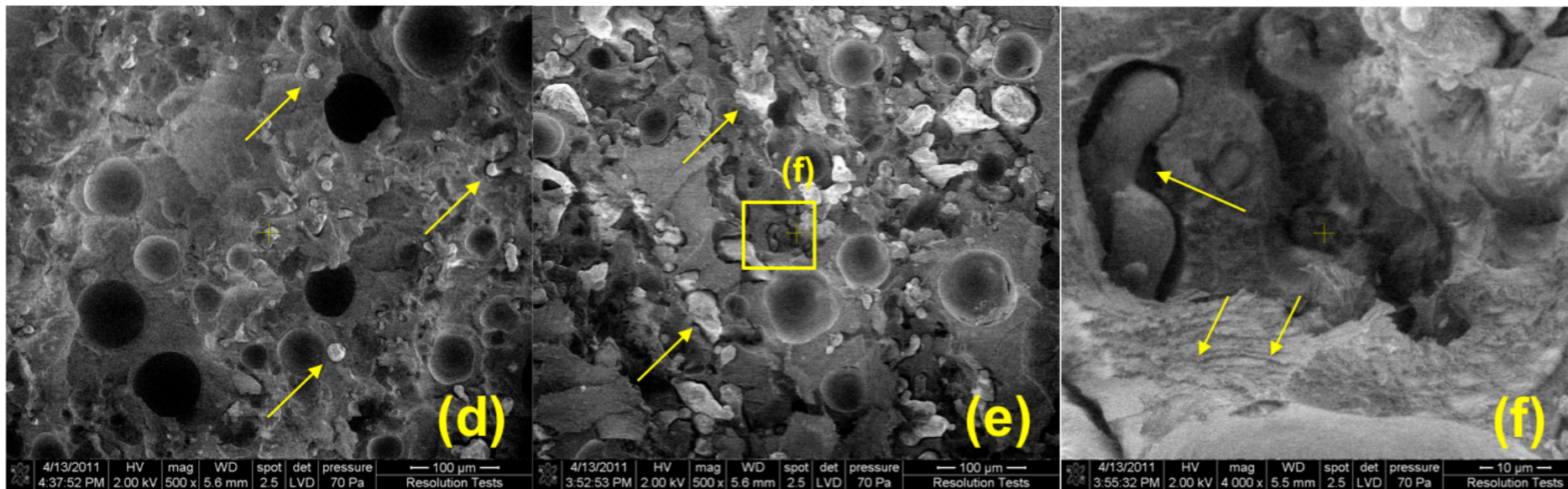
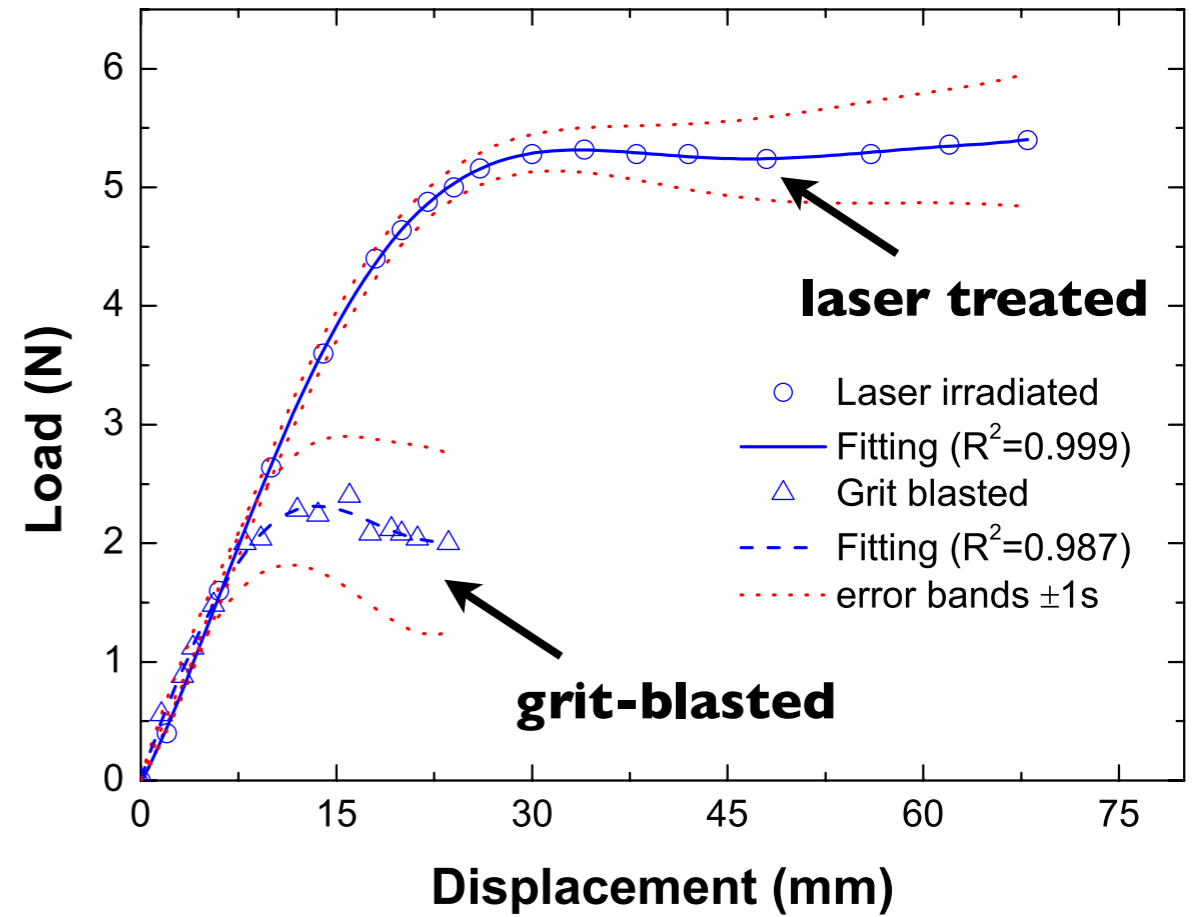
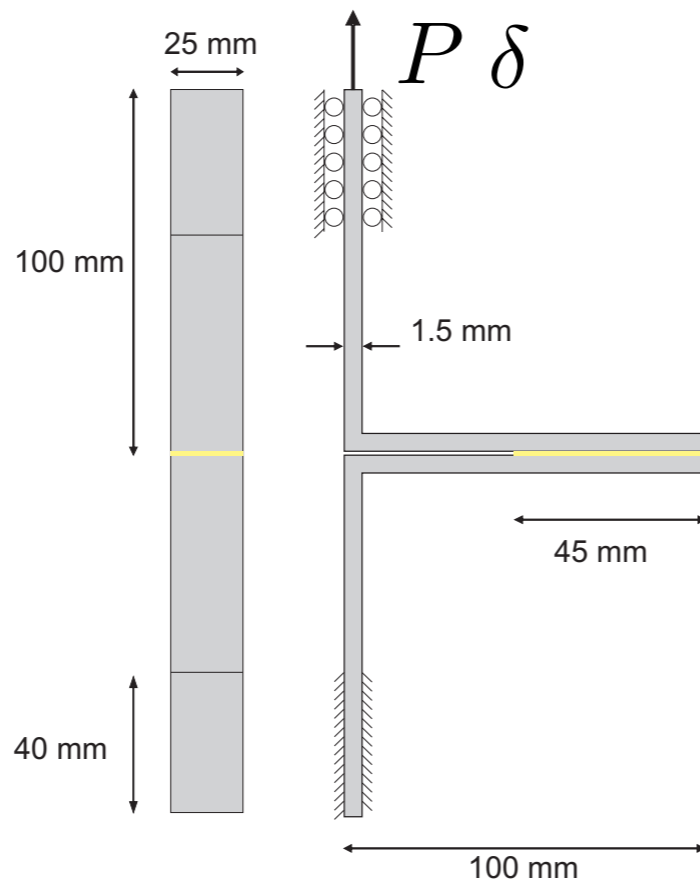
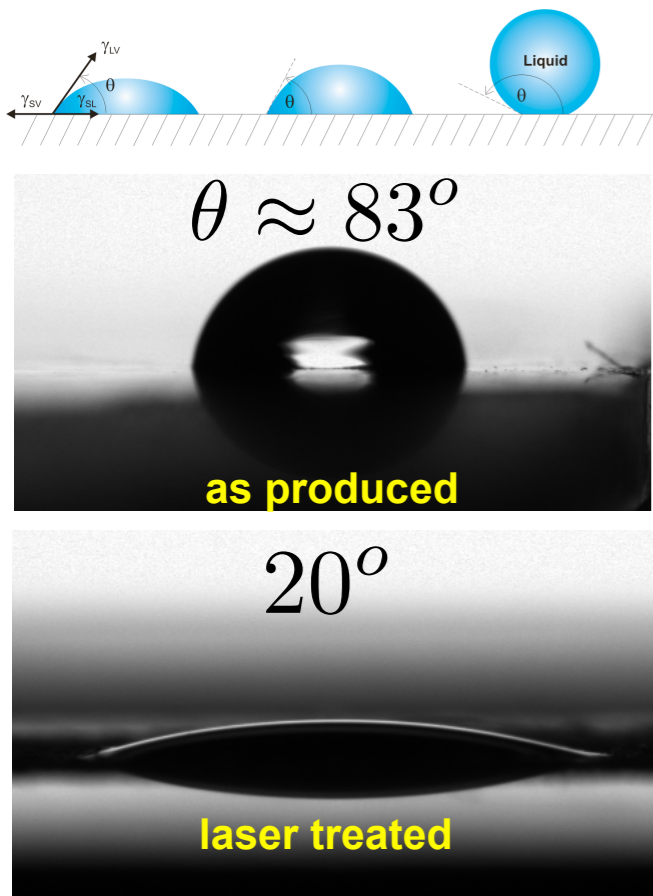
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Minneapolis, July 25th 2011

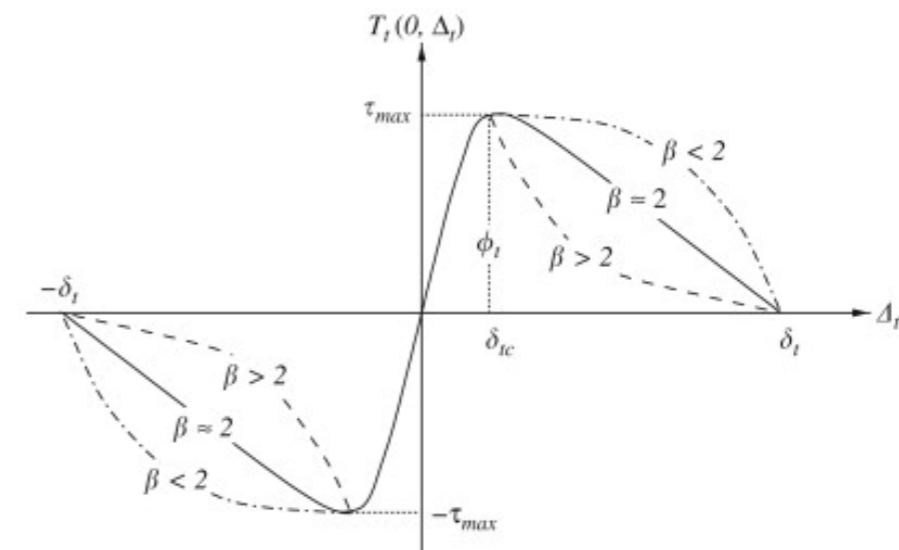
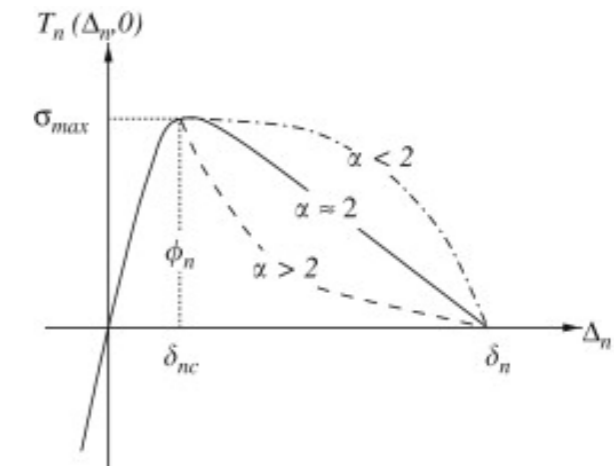
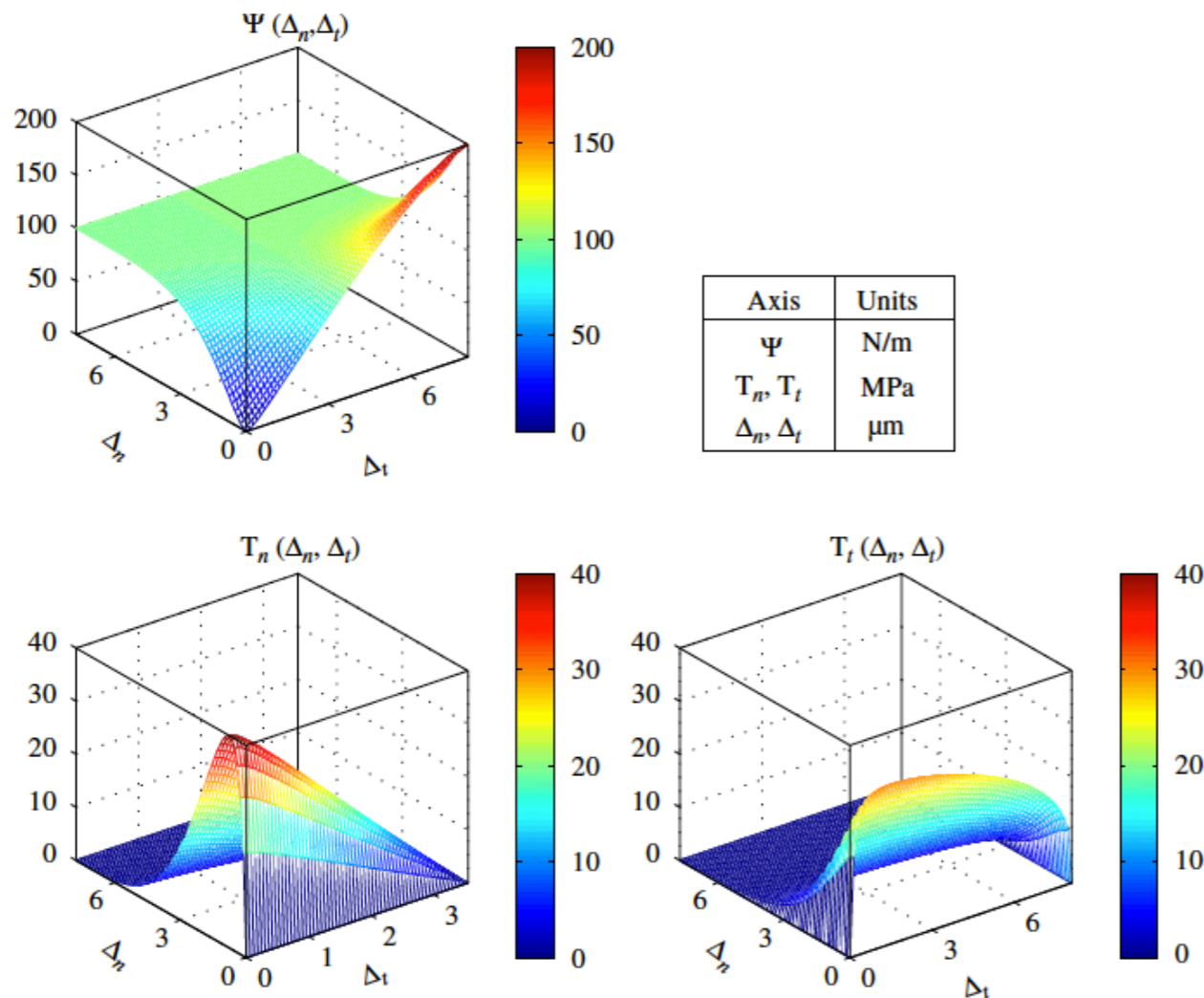
1. Introduction and motivation
2. Objective
3. Proposed approach
4. Algorithm and implementation of the inverse procedure
5. Target applications and experimental set-up (current status)
6. Follow-up work



Alfano M, Furgiuele F, Lubineau G, Paulino GH. Role of laser surface preparation on damage and decohesion of Al/epoxy joints. *Submitted for Journal publication.*

$$\Psi(\Delta_n, \Delta_t) = \min(\phi_n, \phi_t) + \left[\Gamma_n \left(1 - \frac{\Delta_n}{\delta_n} \right)^\alpha \left(\frac{m}{\alpha} + \frac{\Delta_n}{\delta_n} \right)^m + \langle \phi_n - \phi_t \rangle \right] \\ \times \left[\Gamma_t \left(1 - \frac{|\Delta_t|}{\delta_t} \right)^\beta \left(\frac{n}{\beta} + \frac{|\Delta_t|}{\delta_t} \right)^n + \langle \phi_t - \phi_n \rangle \right].$$

- δ_n, δ_t characteristic length scale parameters
- $\bar{\delta}_n, \bar{\delta}_t$ normal and tangential conjugate final crack opening widths
- λ_n, λ_t initial slope indicators
- σ_{max}, τ_{max} normal and tangential cohesive strengths
- ϕ_n, ϕ_t modes I and II fracture energies
- Ψ potential function for cohesive fracture
- α, β shape parameters in the PPR model



Park K, Paulino GH, Roesler JR. A unified potential-based cohesive model of mixed-mode fracture. *Journal of the Mechanics and Physics of Solids*. 2009;57(6):891-908.

$$\Psi(\Delta_n) = \phi_n + \Gamma_n \left(1 - \frac{\Delta_n}{\delta_n}\right)^\alpha \left(\frac{m}{\alpha} + \frac{\Delta_n}{\delta_n}\right)^m$$

$$T(\Delta_n) = \frac{\partial \Psi}{\partial \Delta_n} =$$

$$= \frac{\Gamma_n}{\delta_n} \left[m \left(1 - \frac{\Delta_n}{\delta_n}\right)^\alpha \left(\frac{m}{\alpha} + \frac{\Delta_n}{\delta_n}\right)^{m-1} - \alpha \left(1 - \frac{\Delta_n}{\delta_n}\right)^{\alpha-1} \left(\frac{m}{\alpha} + \frac{\Delta_n}{\delta_n}\right)^m \right]$$

$$\Gamma_n = -\phi_n \left(\frac{\alpha}{m}\right)^m$$

energy constant;

$$m = \frac{\alpha(\alpha-1)\lambda_n^2}{1-\alpha\lambda_n^2}$$

non-dimensional exponent;

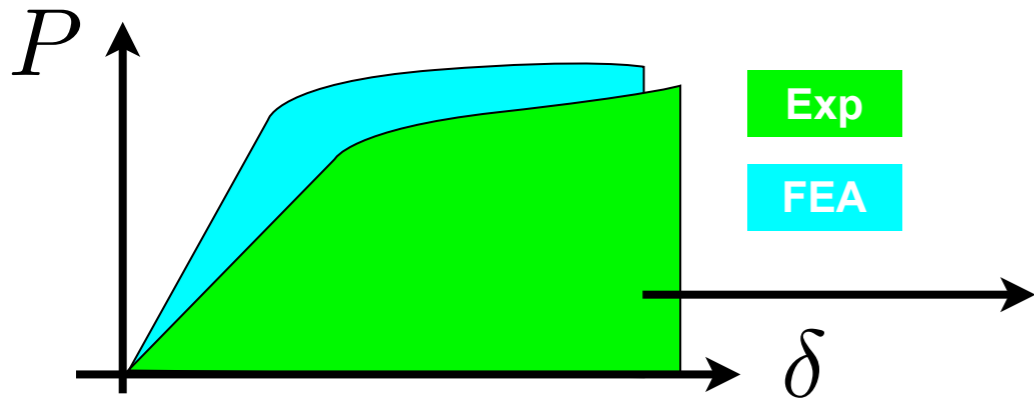
$$\delta_n = \frac{\phi_n}{\sigma_{max}} \alpha \lambda_n (1 - \lambda_n)^{\alpha-1} \left(\frac{\alpha}{m} + 1\right) \cdot$$

final crack opening width;

$$\left(\frac{\alpha}{m} \lambda_n + 1\right)^{m-1}$$

$$\mathbf{X} = \{\phi_n, \sigma_{max}, \lambda_n, \alpha\}$$

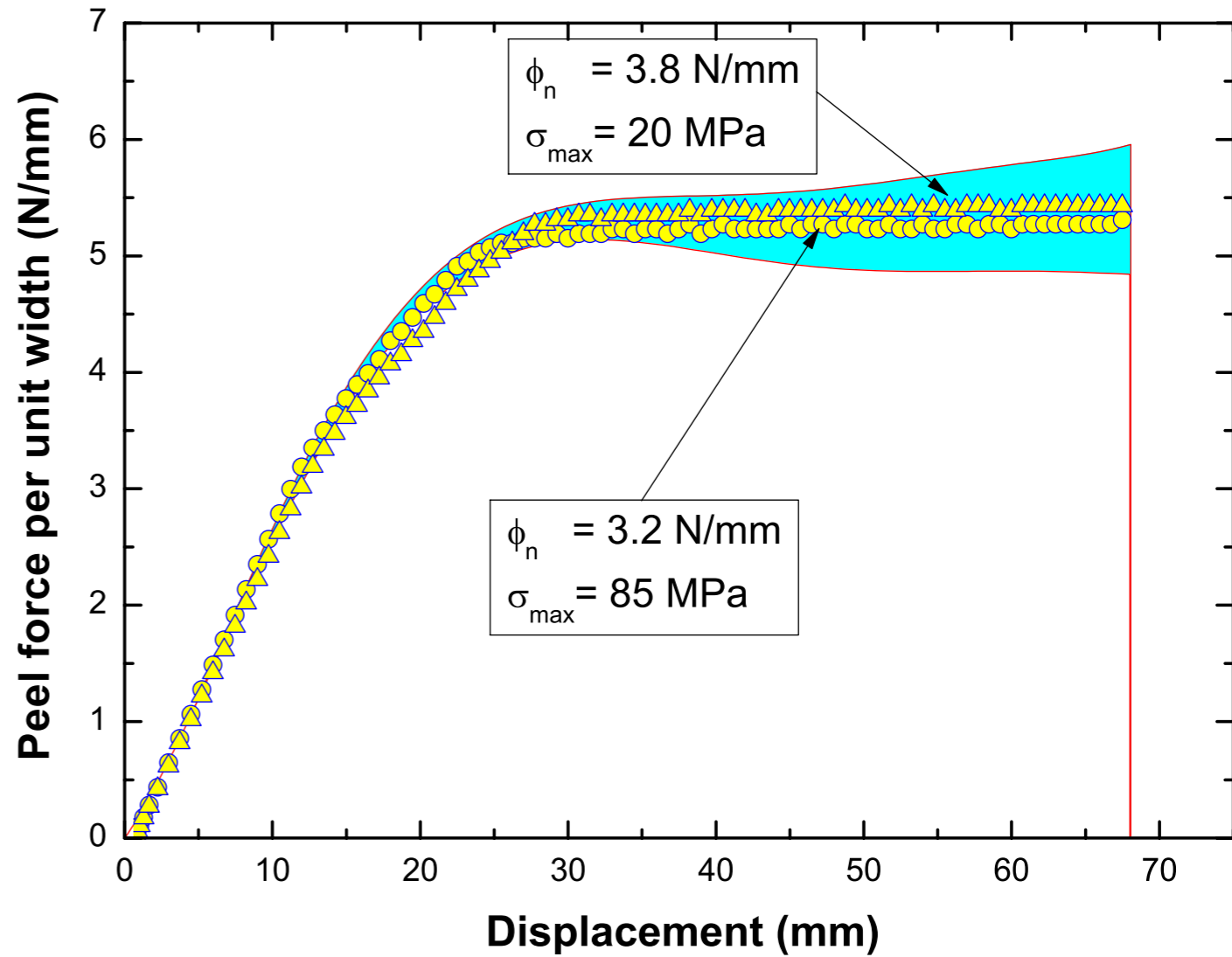
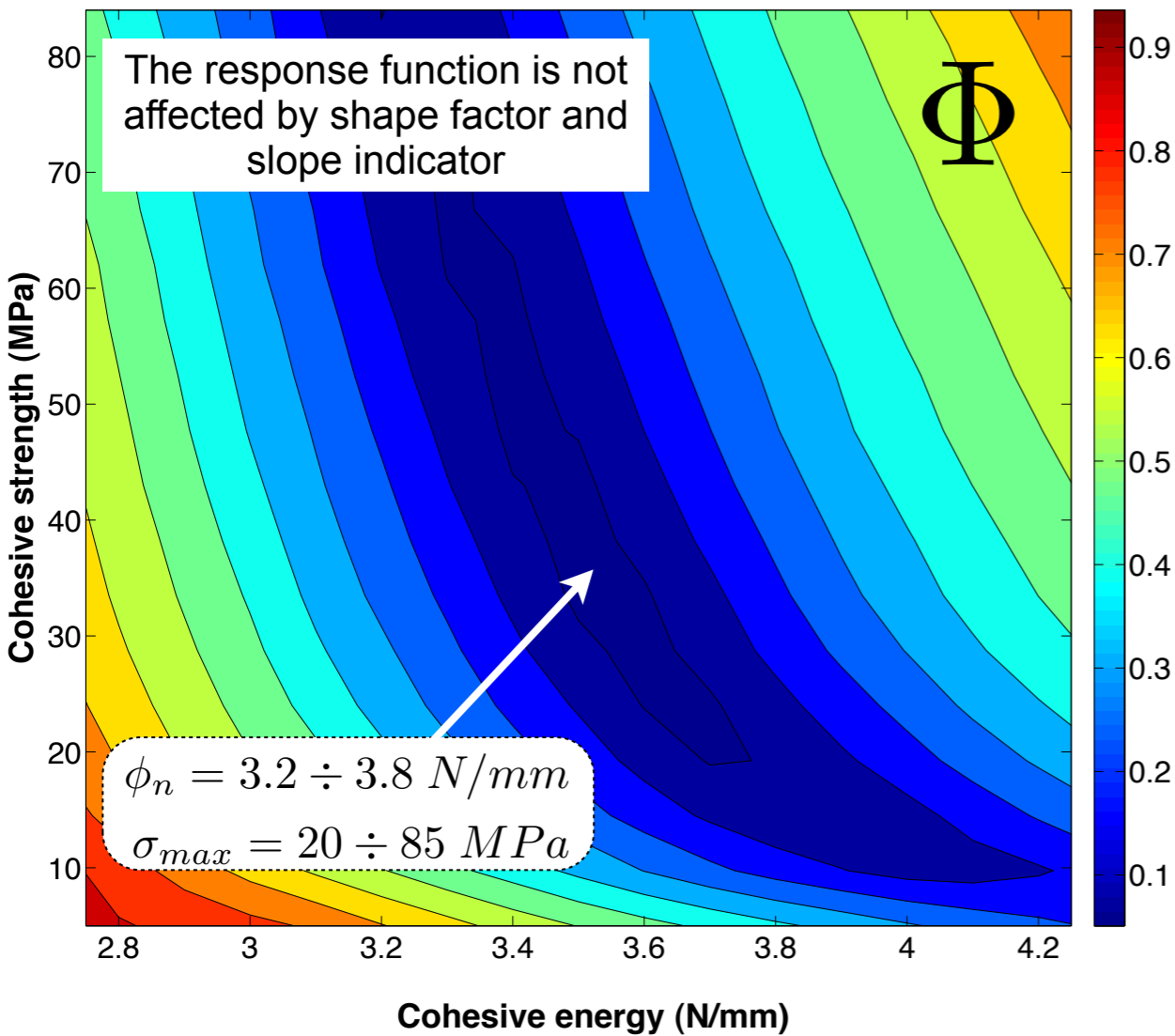
unknown properties to be identified



$$\Phi = \| U(\delta)_{EXP} - U(\delta)_{FE} \|_2$$

$$U(\delta) = \int_{\delta_{i-1}}^{\delta_i} P(\delta) d\delta = (\delta_i - \delta_{i-1}) \times \frac{P(\delta_i) + P(\delta_{i-1})}{2}$$

(b)



Alfano M, Furgiuele F, Lubineau G, Paulino GH. Identification of mode-I cohesive zone parameters of Al / epoxy T-peel joints with laser treated substrates. *Submitted for Journal publication.*

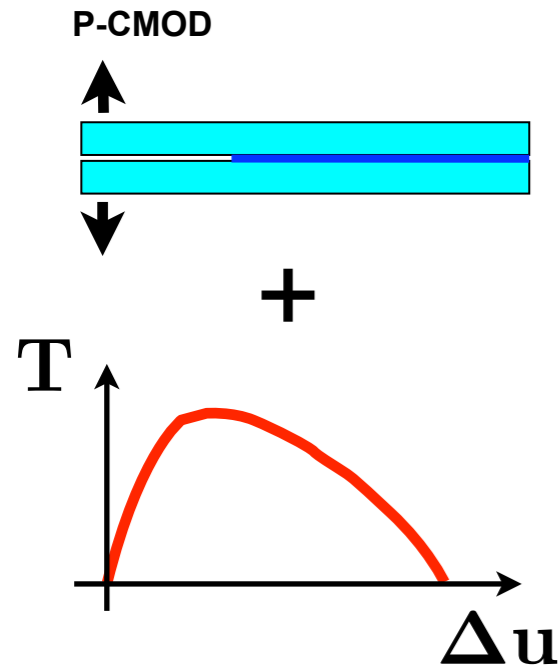
- ➡ A global response is often obtained from experiments, however, it may have low sensitivity to certain cohesive properties.
- ➡ The uniqueness of the obtained cohesive zone model is not guaranteed.

Although the cohesive models obtained using global data can yield satisfactory predictive capabilities in FEA simulations of fracture, the **development of an alternative procedure is needed**, e.g. to determine cohesive strength.

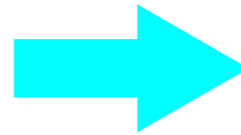
A solution may be provided by the original combination of experimental **full-field measurements** techniques and **inverse problems**.

Gain AL, Carroll J, Paulino GH, Lambros J. A hybrid experimental / numerical technique to extract cohesive fracture properties for mode-I fracture of quasi-brittle materials. *International Journal of Fracture*. 2011;169:113-131.

Shen B, Paulino GH. Direct Extraction of Cohesive Fracture Properties from Digital Image Correlation: A Hybrid Inverse Technique. *Experimental Mechanics*. 2011;51(2):143-161.



Forward problem

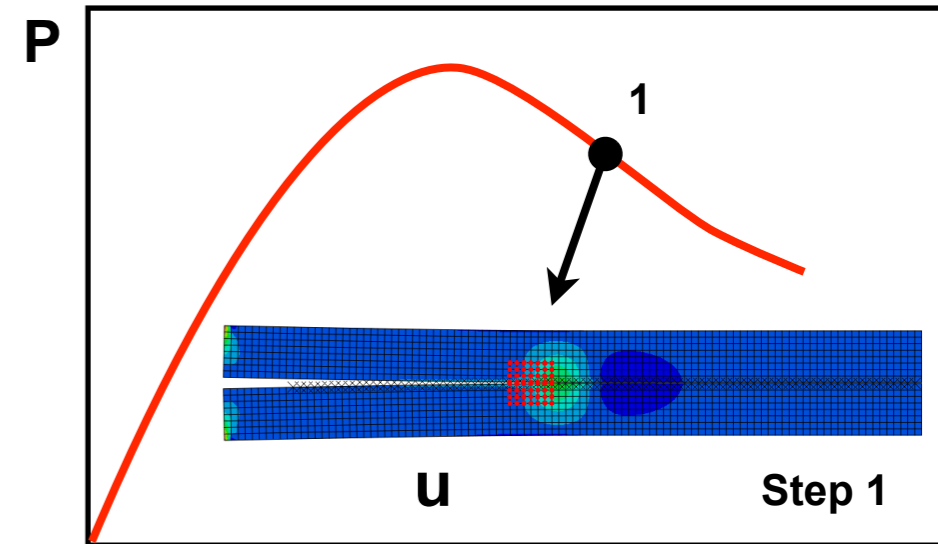


$$(\mathbf{K}_b + \mathbf{K}_c(\mathbf{u}, \mathbf{X}))\mathbf{u} = \mathbf{F}_{ext}$$

$$\mathbf{K}_b = \int_{\Omega} \mathbf{B}^T \mathbf{E} \mathbf{B} d\Omega$$

$$\mathbf{K}_{coh} = \int_{\Gamma_{coh}} \mathbf{N}^T \frac{\partial \mathbf{T}}{\partial \Delta \mathbf{u}} \mathbf{N} d\Gamma_{coh}$$

$$\mathbf{F}_{ext} = \int_{\Gamma_{ext}} \mathbf{T}_{ext} d\Gamma_{ext}$$



CMOD

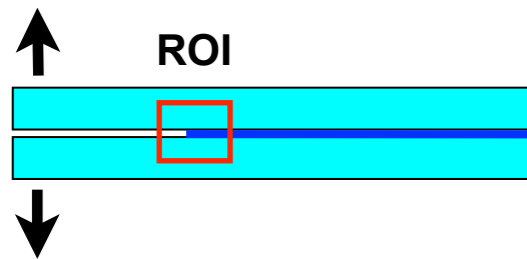
Principle of virtual work

$$\int_{\Omega} \boldsymbol{\sigma} : \delta \boldsymbol{\epsilon} d\Omega - \int_{\Gamma_{ext}} \mathbf{T}_{ext} \cdot \delta \Delta \mathbf{u} d\Gamma_{ext} +$$

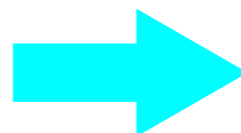
$$- \int_{\Gamma_{coh}} \mathbf{T}_{coh} \cdot \delta \Delta \mathbf{u} d\Gamma_{coh} = 0$$

Ω : specimen domain
 Γ_{ext} : external boundary
 Γ_{coh} : cohesive surfaces
 $\Delta \mathbf{u}$: cohesive surfaces opening displacement
 $\boldsymbol{\sigma}$: stress tensor
 $\boldsymbol{\epsilon}$: strain tensor

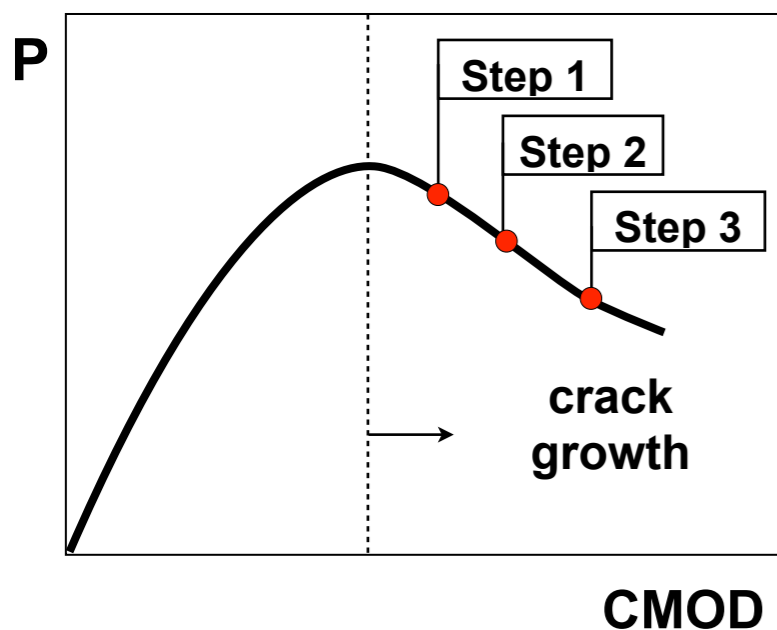
P-CMOD



Inverse problem
(optimization)



$$\mathbf{X} = \{\phi_n, \sigma_{max}, \alpha, \lambda_n\}$$

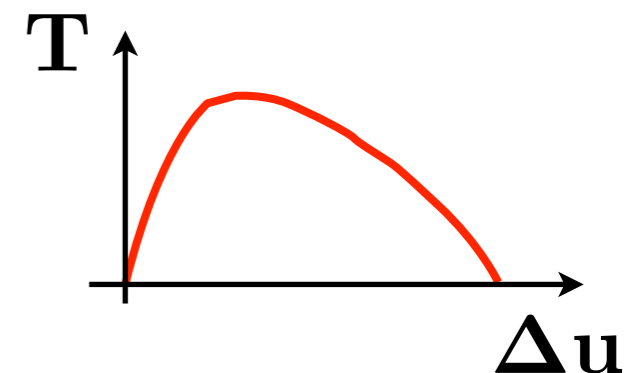


$$\hat{\mathbf{X}} = \arg \min_{\mathbf{X} \in \mathbb{R}^M} \left\{ \Pi = \sum_{i=1}^m \omega_i(\mathbf{X}) \right\}$$

$$\omega_i(\mathbf{X}) = \frac{1}{(U_{max,i})^2} \sum_{j=1}^{n_n} [u_{exp} - u(\mathbf{X})]_j^2$$

m : available measurement instants (load levels)

n_n : nodal displacements in the ROI



$$\mathbf{u}(\mathbf{X}) = \mathbf{K}_b^{-1} \hat{\mathbf{F}}^{ext}(\mathbf{u}_{exp}; \mathbf{X})$$

$$\hat{\mathbf{F}}^{ext}(\mathbf{u}_{exp}; \mathbf{X}) = \mathbf{F}^{ext} - \mathbf{K}_c(\mathbf{u}_{exp}; \mathbf{X}) \mathbf{u}_{exp}$$

Optimization algorithm?

Exploration algorithm based on the mechanism of natural selection and genetics: the strongest **individuals (chromosomes)** in a **population** survive and generate offsprings.

A **chromosome** represents a generic solution of the problem, in our context a set of cohesive fracture parameters (**X**):



Basic steps of the GA

1. Random generation of the **initial population** (individuals **X**) satisfying suitable restraint conditions (e.g. fracture energy must not be negative);

2. The chromosomes are evaluated, using some measures of **fitness**. We defined the following **objective function (or cost function)**:

$$\omega_i(\mathbf{X}) = \frac{1}{(U_{max,i})^2} \sum_{j=1}^{n_n} [u_{exp} - u(\mathbf{X})]_j^2$$

$$\hat{\mathbf{X}} = \arg \min_{\mathbf{X} \in \mathbb{R}^M} \left\{ \Pi = \sum_{i=1}^m \omega_i(\mathbf{X}) \right\}$$

m : available measurement instants (load levels)

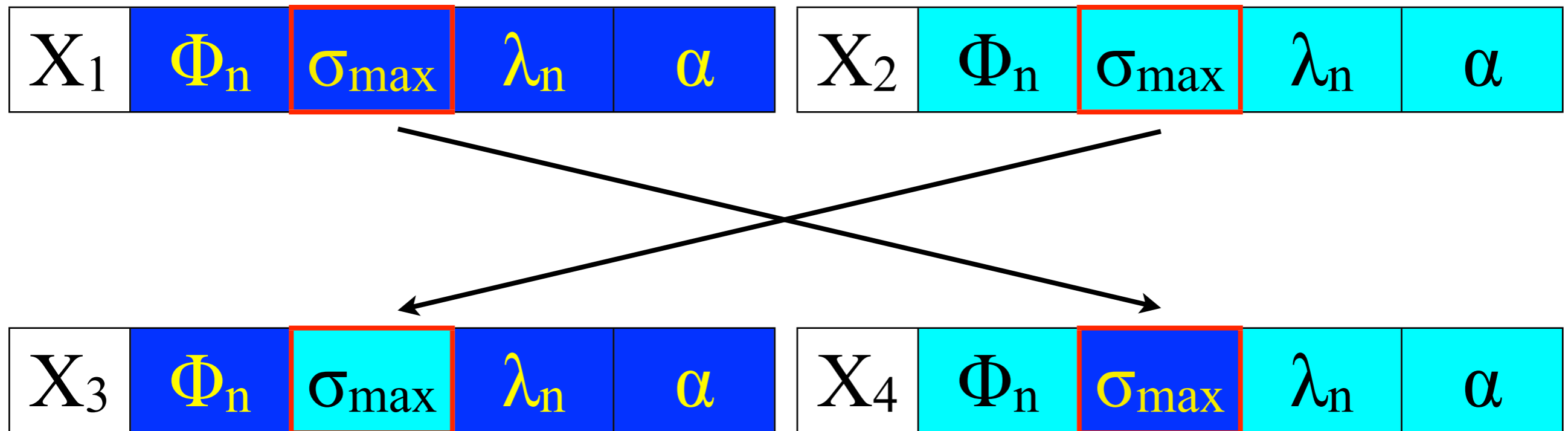
n_n : nodal displacements in the ROI

3. Individuals for **reproduction** are firstly chosen based on their fitness

4. and some of them are processed by means of **genetic operators (crossover and mutation)** to create a new populations

5. New chromosomes, called **offspring**, are formed by merging two chromosomes from current generation

Crossover (type 1)



Crossover (type 2)

$$\mathbf{X}_3 = a \cdot \mathbf{X}_1 + (1 - a) \cdot \mathbf{X}_2$$

$$\mathbf{X}_4 = (1 - a) \cdot \mathbf{X}_1 + a \cdot \mathbf{X}_2$$

$$a \in [0, 1]$$

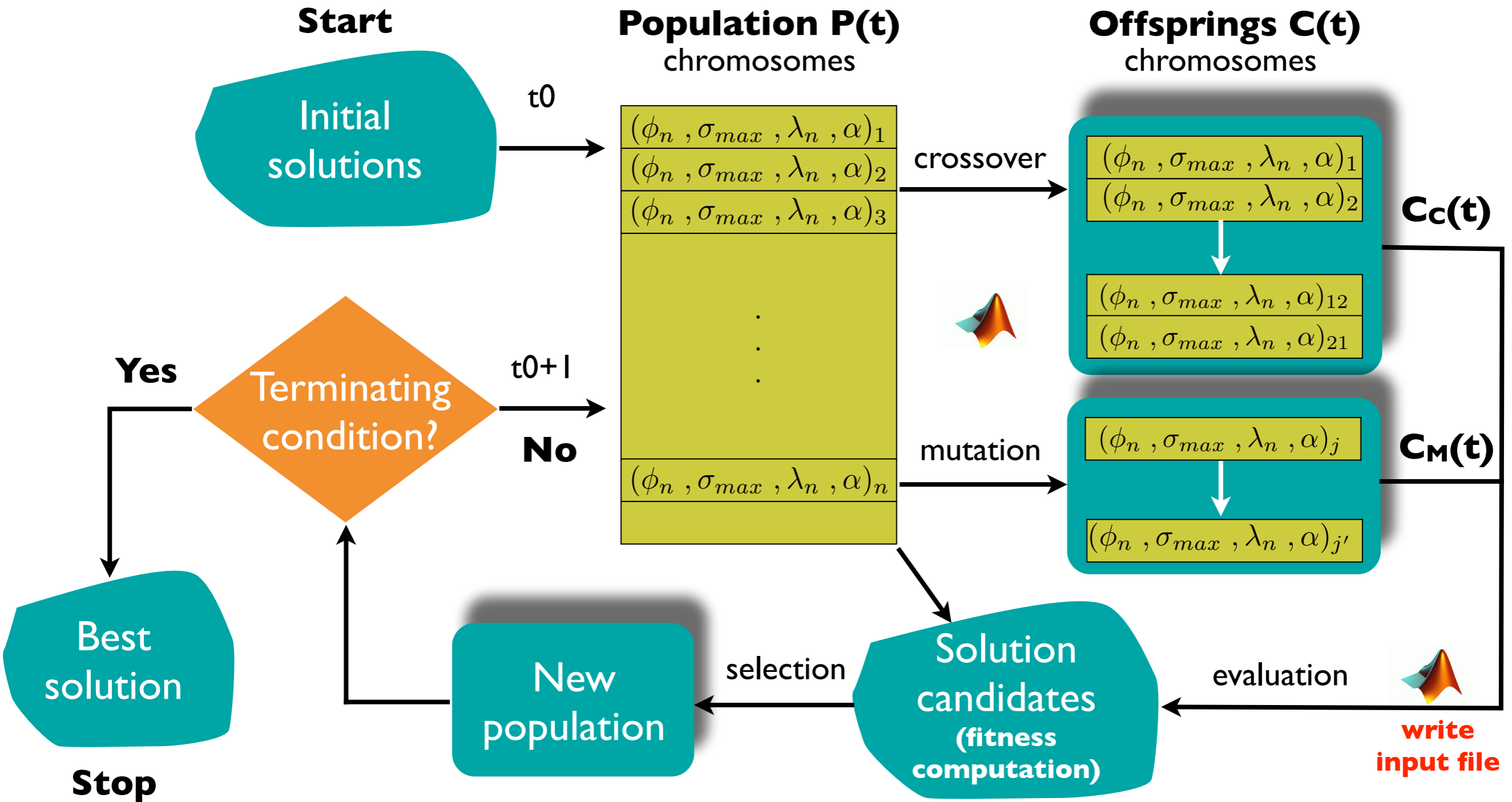
5. New chromosomes are also formed by modifying a chromosome using a mutation operator




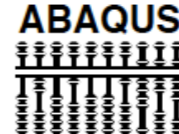
$$\sigma'_{max} = \sigma_{max} + r \cdot \Delta\sigma_{max}$$
$$r \in [-1, 1], \Delta\sigma_{max} = cost.$$



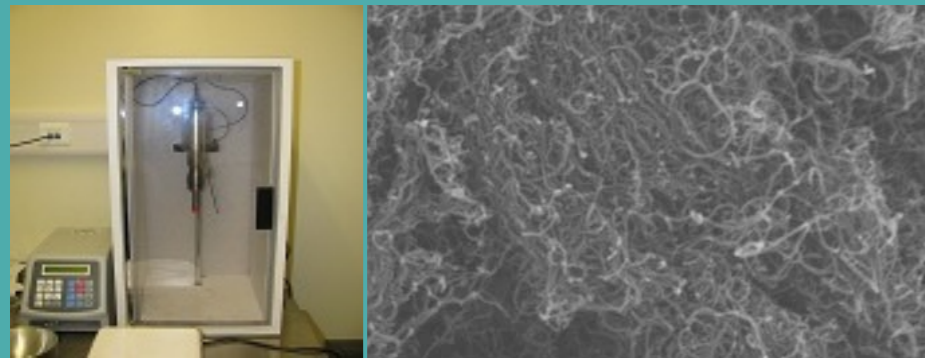
6. The newly created population replace the old one and the process restarts.



**Abaqus/Matlab interaction
by means of Linux shell scripts**

 + 
read output file + **solve non-linear fracture problem**

Material processing - DCB with metal and composites substrates



**Ultrasonic
Dispersion**

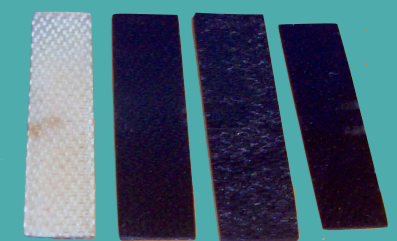
**MWCNT
Dispersion**



**Hot press
15T/300°C**



**Specialized
cutting devices**



**Composite
laminates**

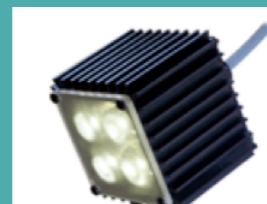
Full-field experimental measurements



**INSTRON Testing
machine**



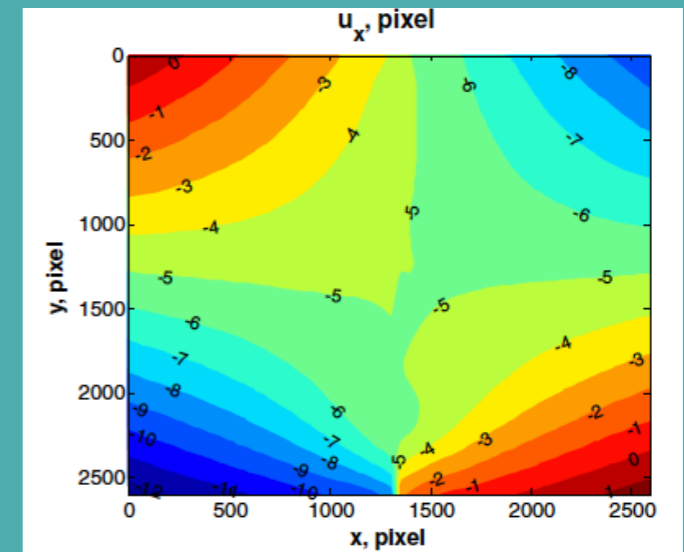
**High
resolution
CCD camera
(PixelFly)**



**High intensity
Led spotlight**



**QMI00 long distance microscope
(QUESTAR)**



In-house developed DIC algorithm

King Abdullah University of
Science and Technology



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