

# Stable Topology Optimization with Arbitrary Polygons

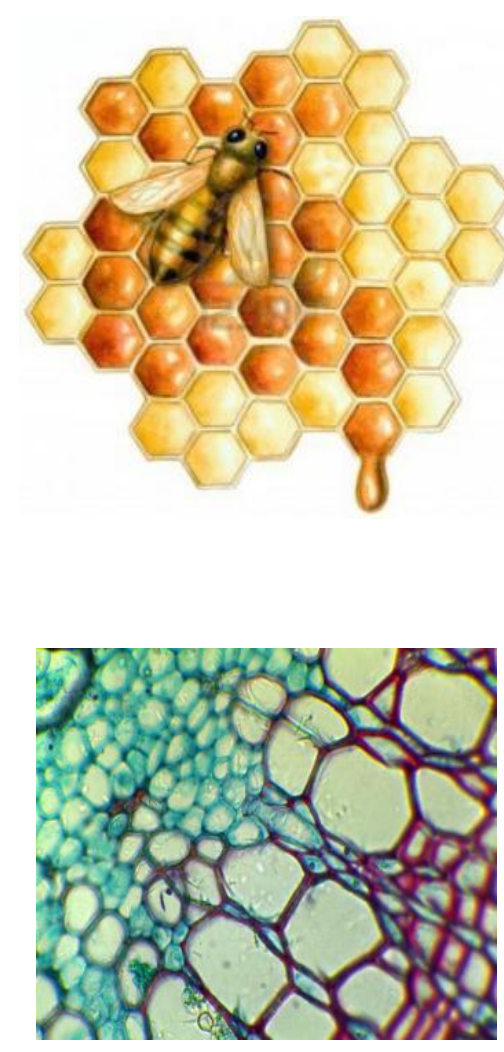
Heng Chi, Glaucio H. Paulino

Civil and Environmental Engineering Department, University of Illinois, Urbana, IL, USA

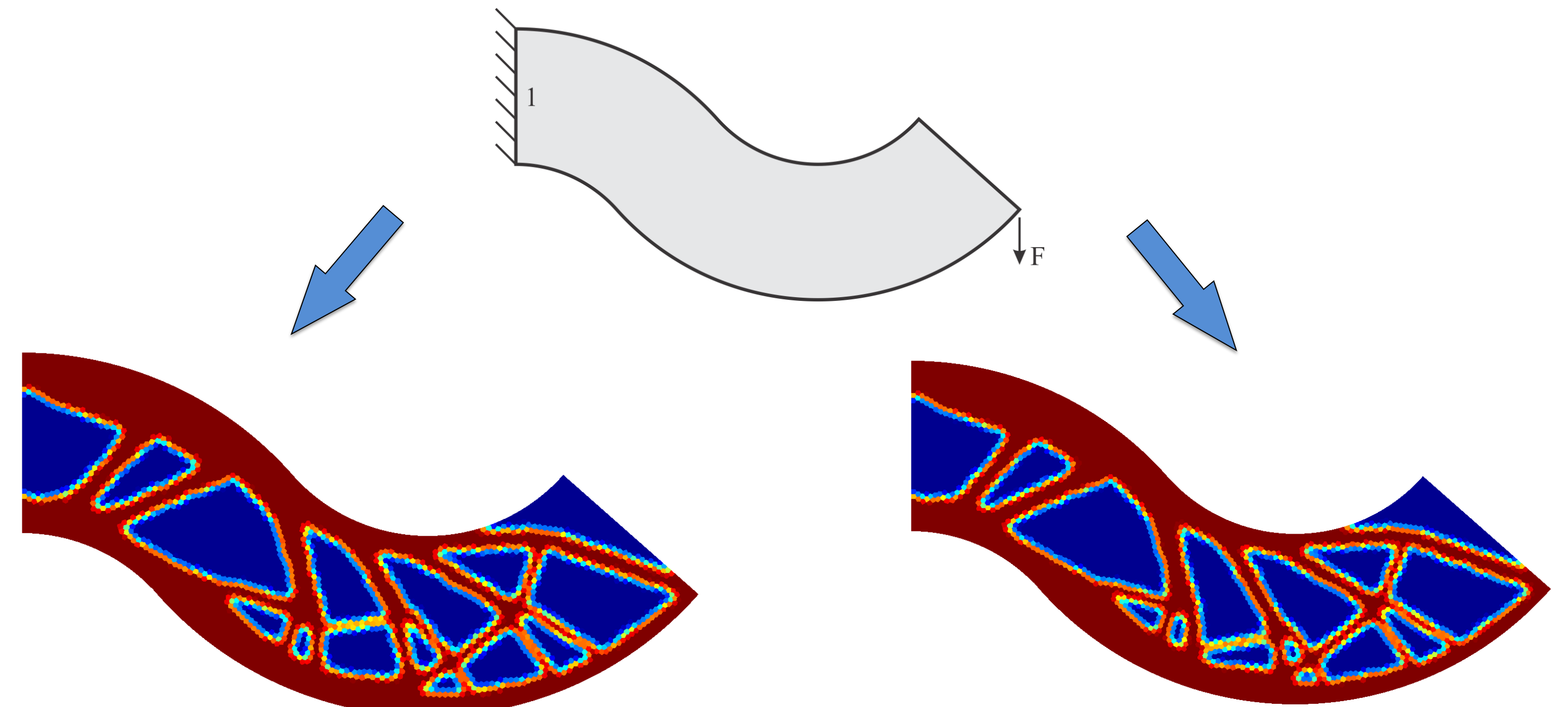


## Motivation

- ❑ Polygonal elements are nature inspired
- ❑ Polygonal elements can alleviate mesh bias and produce optimal topologies
- ❑ To handle arbitrary/degenerate polygons, available techniques are less accurate and inefficient
- ❑ Virtual Element Method (VEM), provides stable and efficient alternative



## Topology Optimization with CVT Polygons

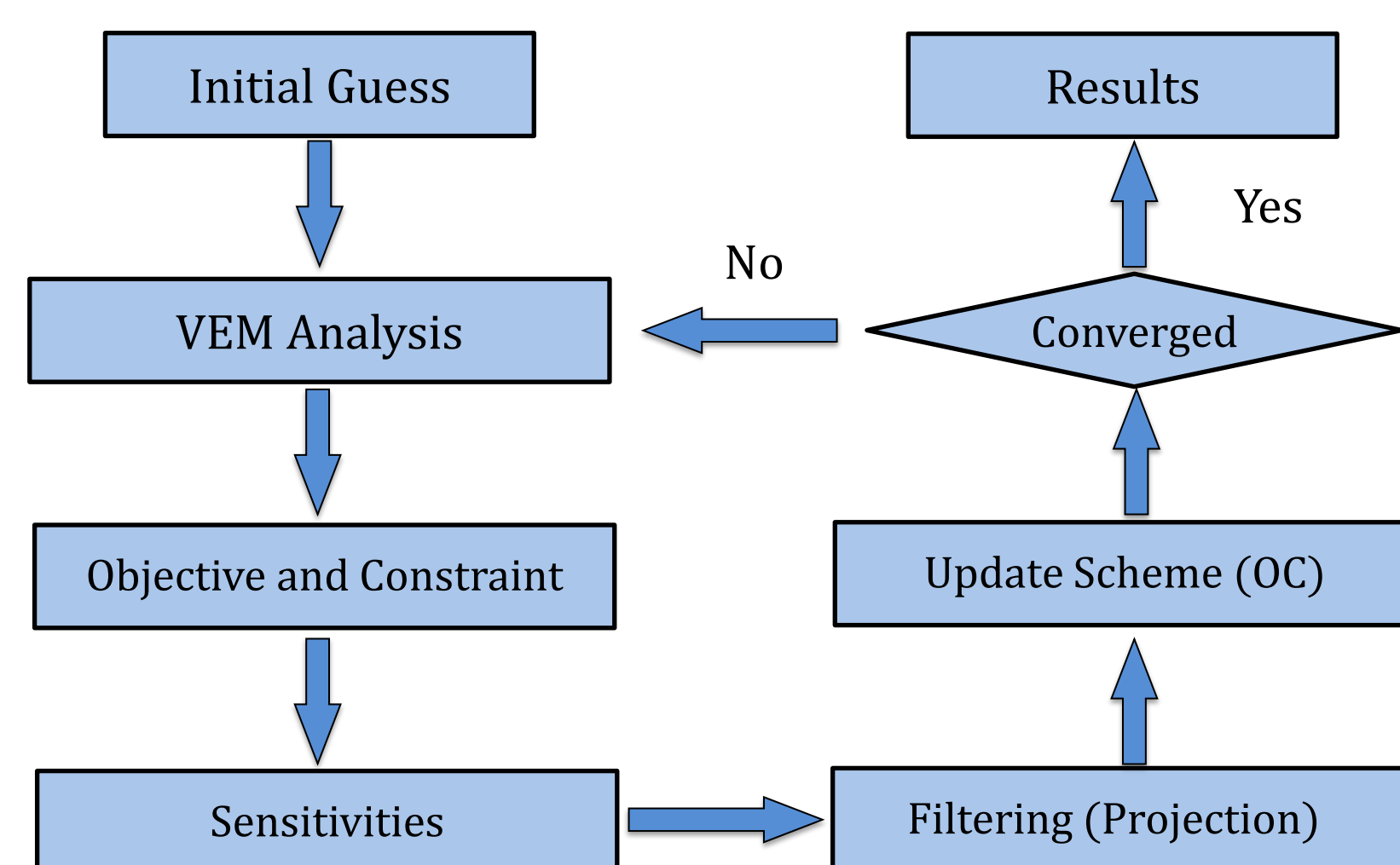


Optimization with VEM formulation  
Objective:361.988

Optimization with PolyFEM formulation  
Objective:362.023

## Optimization Formulation

$$\begin{aligned} \min \quad & \mathbf{f}^T \mathbf{u} \\ \text{s.t.} \quad & \mathbf{K}(E_e) \mathbf{u} = \mathbf{f} \\ & \sum_{e=1}^N V_e \leq V_{max} \\ & 0 < \rho_{min} \leq \rho < 1 \end{aligned}$$



## Virtual Element Method Formulation

- ❑ Two basic properties are required to be satisfied:
  1. Consistency:  $a_h^E(\mathbf{p}_1, \mathbf{v}) = a^E(\mathbf{p}_1, \mathbf{v}) \forall E, \forall \mathbf{v} \in V^E, \forall \mathbf{p}_1 \in P_1(E)$
  2. Stability:  $\exists \alpha^*, \alpha_* > 0, \exists \alpha_* a^E(\mathbf{v}, \mathbf{v}) \leq a_h^E(\mathbf{v}, \mathbf{v}) \leq \alpha^* a^E(\mathbf{v}, \mathbf{v}) \forall E, \forall \mathbf{v} \in V^E$

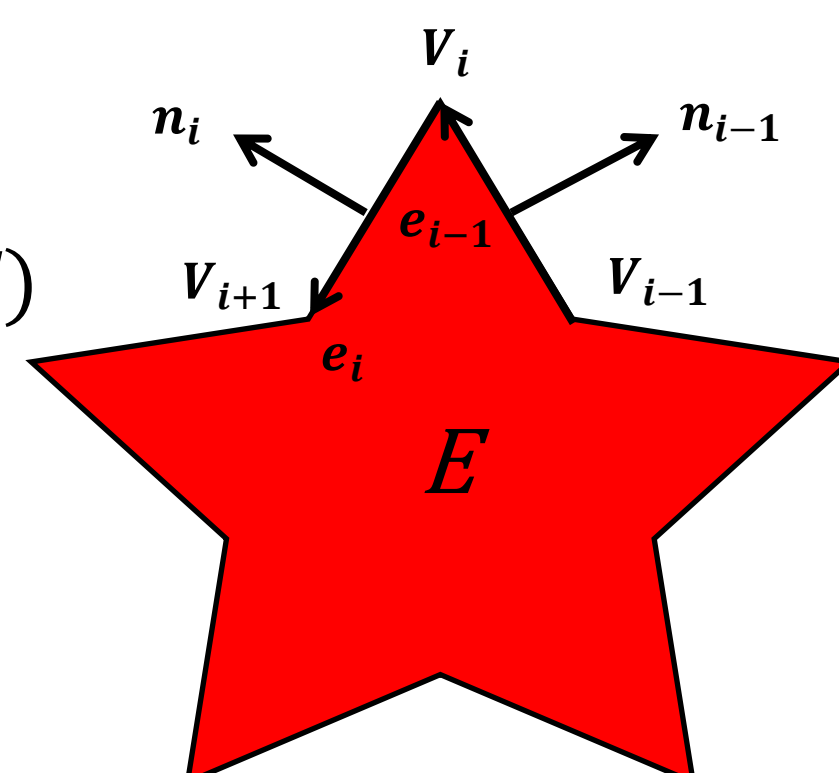
- ❑ Consistency can be ensured by exact integration:

$$a_h^E(\mathbf{p}_1, \mathbf{v}) = \int_{\Omega^E} \nabla \mathbf{p}_1 : \mathbf{C} : \nabla \mathbf{v} d\Omega^E = \int_{\partial\Omega^E} (\nabla \mathbf{p}_1 : \mathbf{C} \cdot \mathbf{v}) \cdot \mathbf{n} d\partial\Omega^E$$

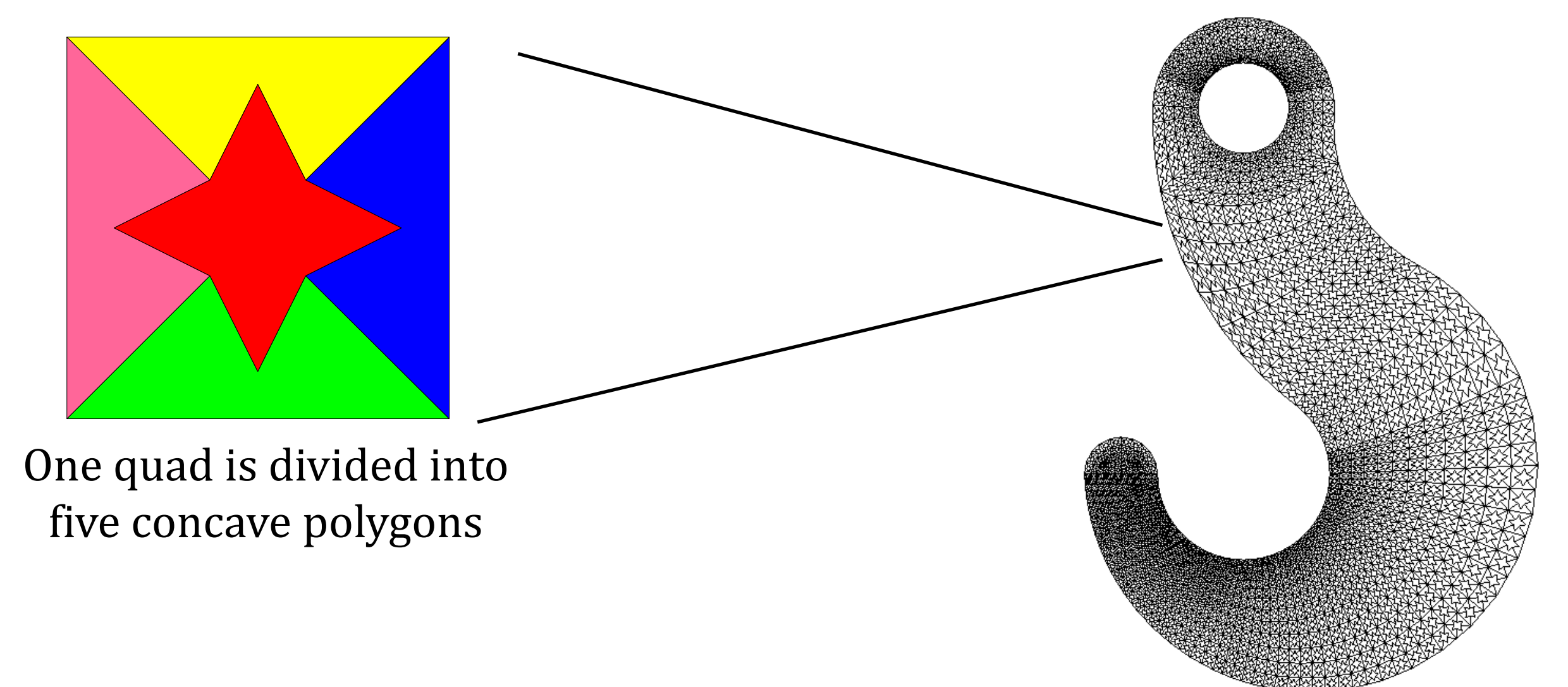
- ❑ A projection operator is defined:  $\Pi: V_h^E \rightarrow P_1(E)$ :  
Such that:  $a^E(\Pi \mathbf{v}_h, \mathbf{q}) = a^E(\mathbf{v}_h, \mathbf{q})$  and  $\Pi \mathbf{q} = \mathbf{q} \forall \mathbf{q} \in P_1(E)$

- ❑ Finally, we get:

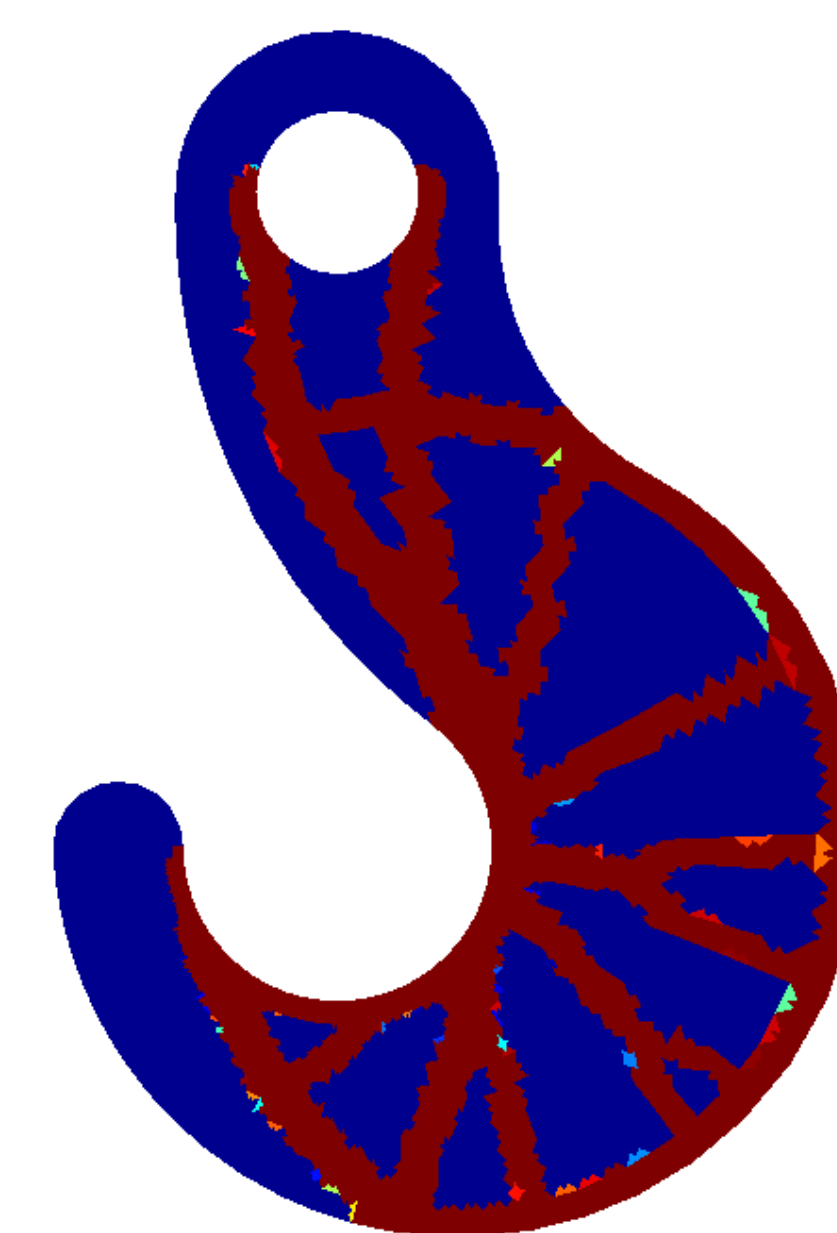
$$a_h^E(\mathbf{u}_h, \mathbf{v}_h) = a^E(\Pi \mathbf{u}_h, \Pi \mathbf{v}_h) + (I - \Pi) s^E(\mathbf{u}_h, \mathbf{v}_h) (I - \Pi)$$



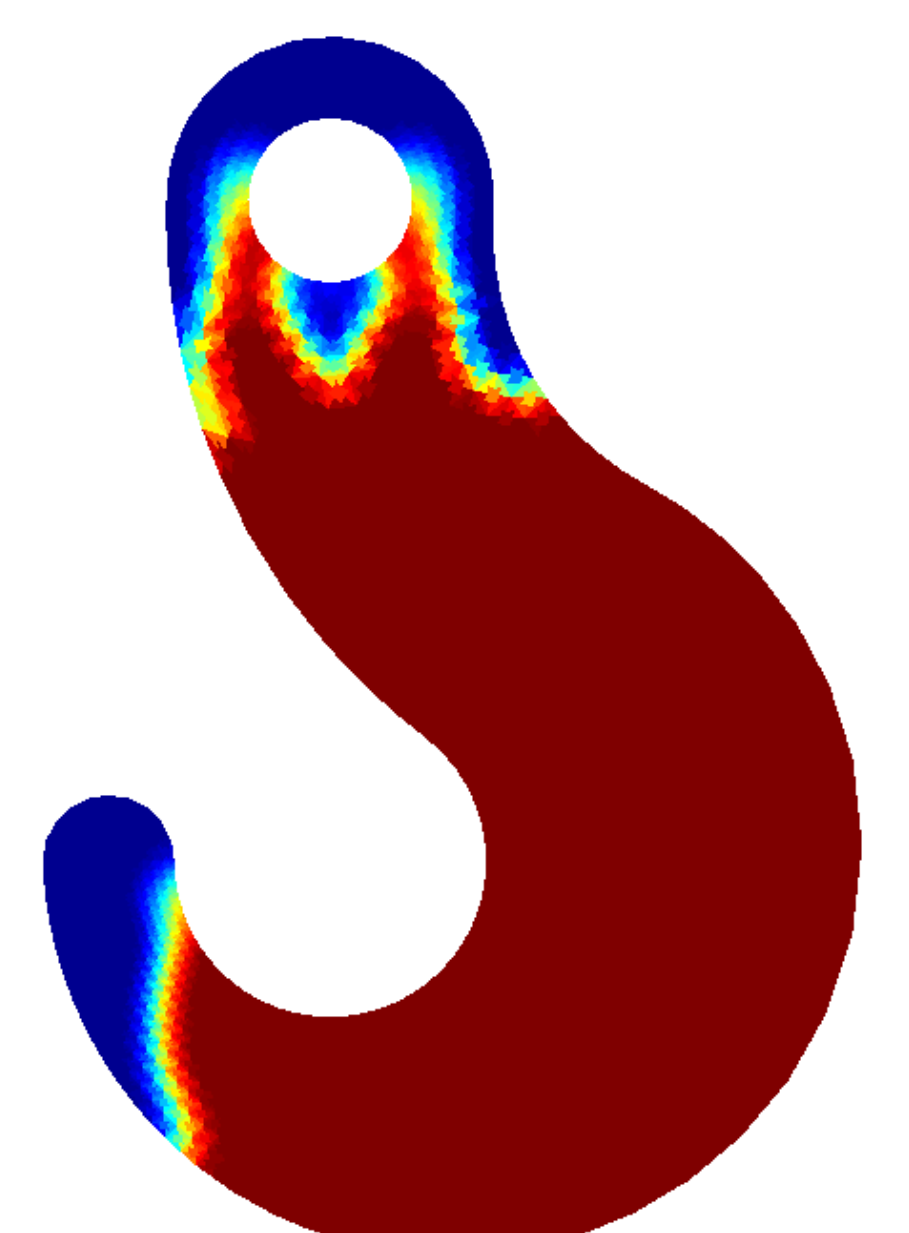
## Topology Optimization with Concave Polygons



One quad is divided into five concave polygons



Optimization with VEM formulation  
Objective:2805.697



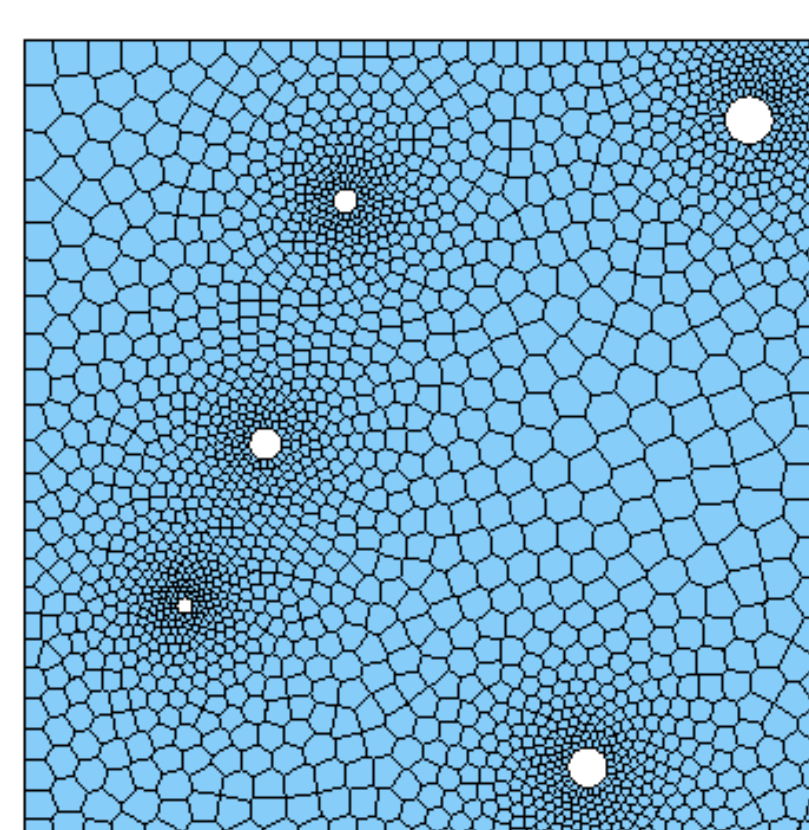
Optimization with PolyFEM formulation  
Objective: 267223.208

## Conclusion

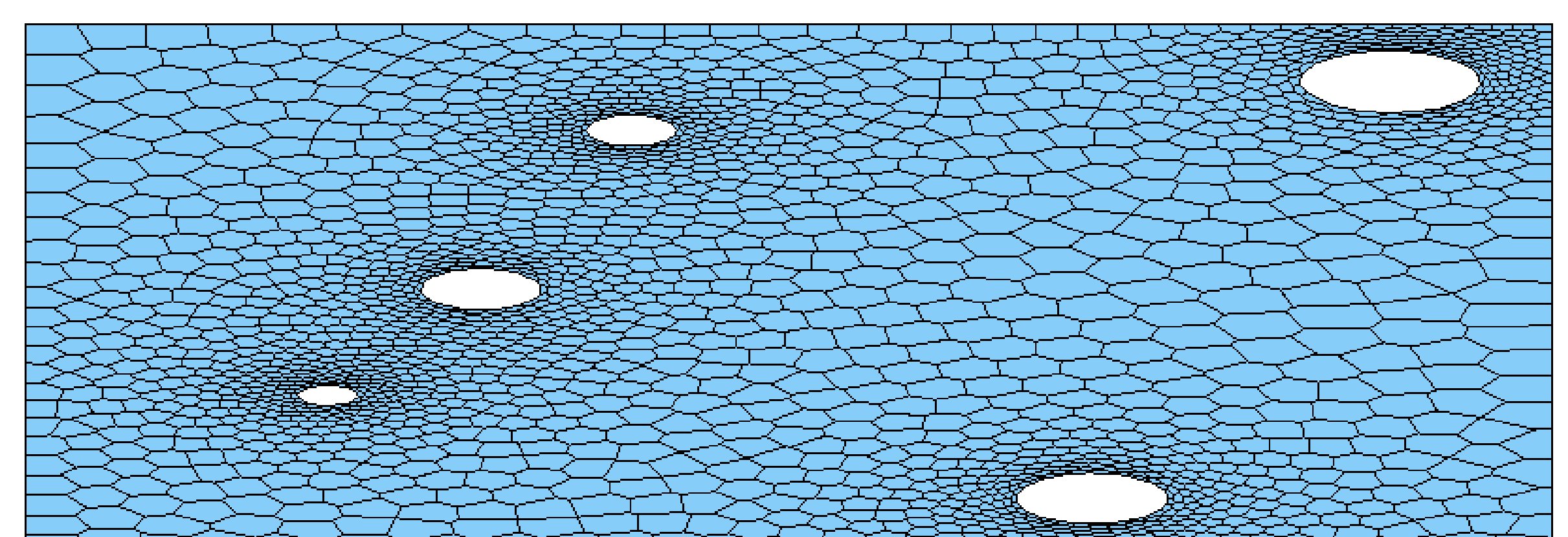
- ❑ For regular polygonal mesh, PolyFEM and VEM formulation yields similar optimal design with very close compliance
- ❑ For concave/degenerate polygonal mesh, VEM result is stable while traditional PolyFEM results is numerically unstable
- ❑ VEM formulation allows more flexibility for the shape of elements in topology optimization

## Future Work

- ❑ Topology optimization with geometrical and material nonlinearity with arbitrary polygons
- ❑ Nonlinear topology optimization for multi-physics and multi-scale problems



$$\mathbf{x} = \phi(\mathbf{X})$$



## Reference

1. C. Talischi, G.H.Paulino, A.Pereira, I.F.M.Menezes. PolyTop: a Matlab implementation framework using unstructured polygonal finite element meshes. Struct Multidisc Optim (2012) 45:329-357
2. C. Talischi, G.H.Paulino, A.Pereira, I.F.M.Menezes. PolyMesher: a general-purpose mesh generator for polygonal elements written in Matlab. Struct Multidisc Optim (2012) 45:309-328
3. L. Beirão da Veiga, F. Brezzi, A. Cangiani, G. Manzini, L.D. Marini, A. Russo: Basic principles of Virtual Element Methods, Math. Models Methods Appl. Sci (2013) 23:199-214
4. L. Beirão da Veiga, F. Brezzi, L.D. Marini: Virtual Elements for linear elasticity problems SIAM J. Num. Anal. (2013) 81: 794-812