

# Topology Optimization Considering the Drucker–Prager Criterion Using a Surrogate Nonlinear Elastic Constitutive Model

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# Motivation

- The flow theory of plasticity [Hill, 1950; Bell, 1968; Lubliner, 1992]:

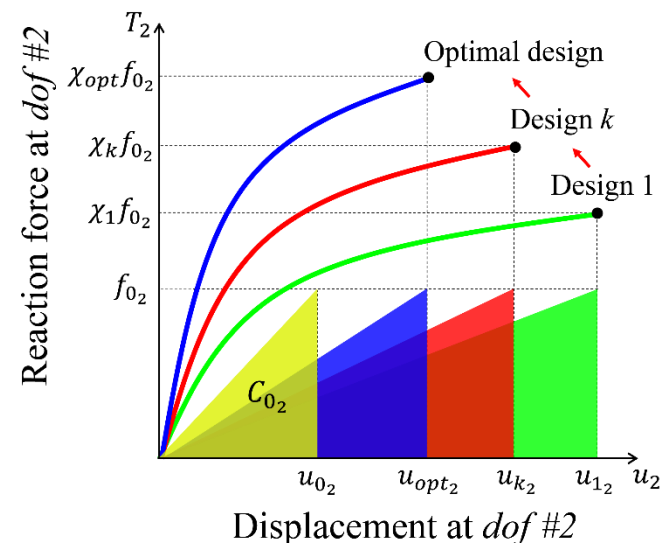
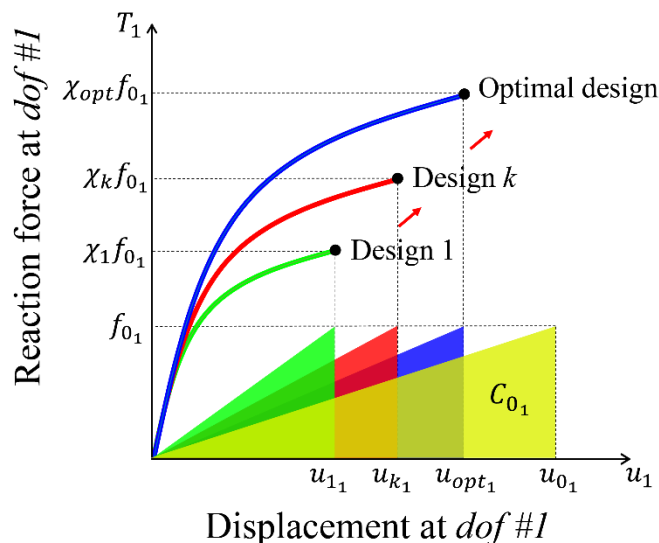
The behavior of the plastic materials is characterized by **NONLINEARITY** and **PATH-DEPENDENT** physical processes (i.e., energy dissipation & unloading).

- Generalized  $J_2$  deformation theory of plasticity [Hencky, 1924; Drucker and Prager, 1952; Chen and Han 1988; Sonato et al., 2015]:

**A surrogate nonlinear elastic model:**

$$\sigma = \lambda(J_1(\boldsymbol{\varepsilon}), J_2(\boldsymbol{\varepsilon}_d)) J_1(\boldsymbol{\varepsilon}) \mathbf{I} + 2\mu(J_1(\boldsymbol{\varepsilon}), J_2(\boldsymbol{\varepsilon}_d)) \boldsymbol{\varepsilon}$$

- Assuming small deformation, the **nonlinear elastic solution** is equivalent to the **plastic solution** under proportional loading.
- Nonlinear FEM analysis: **Energy control** approach



# Formulations and Sensitivity analyses

## □ Max. structural strain energy

$$\begin{array}{ll}
 \max_{\boldsymbol{\rho}} & J_U(\boldsymbol{\rho}) = U(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) \\
 \text{s. t.} & V \leq V_0 \\
 & 0 \leq \rho_i \leq 1 \\
 \text{with} & \\
 \left\{ \begin{array}{l} \mathbf{T}(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) = \chi(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) \mathbf{f}_0 \\ \mathbf{f}_0^T \mathbf{u}(\boldsymbol{\rho}) = 2C_0 \end{array} \right. & \\
 \left\{ \begin{array}{l} \min_{\mathbf{u}} \quad U(\mathbf{u}) \\ \text{s. t.} \quad \mathbf{f}_0^T \mathbf{u} = 2C_0 \end{array} \right. &
 \end{array}$$

$$\frac{dJ_U(\boldsymbol{\rho})}{d\rho_i} = \frac{\partial U(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho}))}{\partial \rho_i}$$

## □ Max. load factor

$$\begin{array}{ll}
 \max_{\boldsymbol{\rho}} & J_\chi(\boldsymbol{\rho}) = \chi(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) \\
 \text{s. t.} & V \leq V_0 \\
 & 0 \leq \rho_i \leq 1 \\
 \text{with} & \\
 \left\{ \begin{array}{l} \mathbf{T}(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) = \chi(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) \mathbf{f}_0 \\ \mathbf{f}_0^T \mathbf{u}(\boldsymbol{\rho}) = 2C_0 \end{array} \right. & \\
 \left\{ \begin{array}{l} \min_{\mathbf{u}} \quad U(\mathbf{u}) \\ \text{s. t.} \quad \mathbf{f}_0^T \mathbf{u} = 2C_0 \end{array} \right. &
 \end{array}$$

$$\frac{dJ_\chi(\boldsymbol{\rho})}{d\rho_i} = \frac{\left(\frac{\partial \mathbf{T}}{\partial \rho_i}\right)^T (\mathbf{K}_T)^{-1} \mathbf{f}_0}{\mathbf{f}_0^T (\mathbf{K}_T)^{-1} \mathbf{f}_0}$$

Niu F, Xu S, Cheng G. (2011). A general formulation of structural topology optimization for maximizing structural stiffness. *Struct Multidiscip Optim*, 43(4):561–572.

Klarbring A, Strömberg N. (2013). Topology optimization of hyperelastic bodies including nonzero prescribed displacements. *Struct Multidiscip Optim*, 47(1):37–48.

Zhao T, Ramos Jr. AS, Paulino GH. (2019). Material Nonlinear Topology Optimization Considering the von Mises Criterion through an Asymptotic Approach: Max Strain Energy and Max Load Factor Formulations. *Int J Numer Methods Eng*, 118:804-828.

# A surrogate nonlinear elastic model

## □ Drucker-Prager yield function

$$f(\boldsymbol{\sigma}) = \beta J_1(\boldsymbol{\sigma}) + \sqrt{J_2(\boldsymbol{s}(\boldsymbol{\sigma}))} - k_s \quad \text{where} \quad \beta = \frac{1}{2\sqrt{3}} \frac{(1-2\nu^p)}{(1+\nu^p)} \ \& \ k_s = \left(\beta + \frac{1}{\sqrt{3}}\right) \sigma_y$$

## □ Nonlinear elastic constitutive relationship

$$\boldsymbol{\sigma} = \lambda J_1(\boldsymbol{\varepsilon}) \mathbf{I} + 2\mu \boldsymbol{\varepsilon}$$

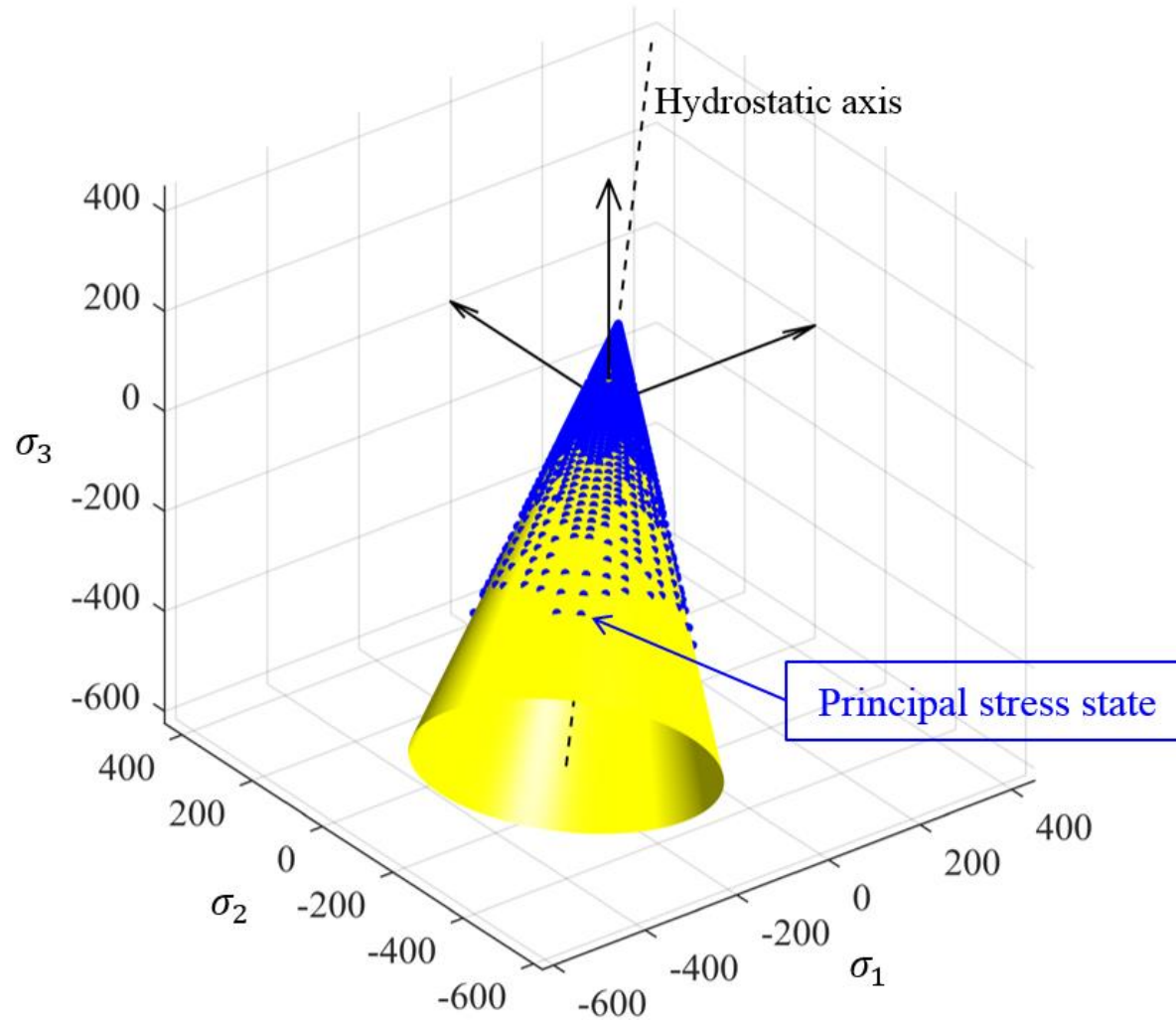
$$\lambda(\phi_1, \phi_2) = \frac{3\nu + (\phi_2 - \phi_1)E}{3(1 + \nu + \phi_2 E)(1 - 2\nu + \phi_1 E)} E \quad \mu(\phi_2) = \frac{E}{2(1 + \nu + \phi_2 E)}$$

$$\phi_1(J_1(\boldsymbol{\varepsilon}), J_2(\boldsymbol{\varepsilon}_d)) = \frac{6\beta\{3\beta(1 + \nu)EJ_1(\boldsymbol{\varepsilon}) + (1 - 2\nu)[3E\sqrt{J_2(\boldsymbol{\varepsilon}_d)} - (3\beta + \sqrt{3})(1 + \nu)\sigma_y]\}}{E[3E(J_1(\boldsymbol{\varepsilon}) - 6\beta\sqrt{J_2(\boldsymbol{\varepsilon}_d)}) + 6\beta(3\beta + \sqrt{3})(1 + \nu)\sigma_y]}$$

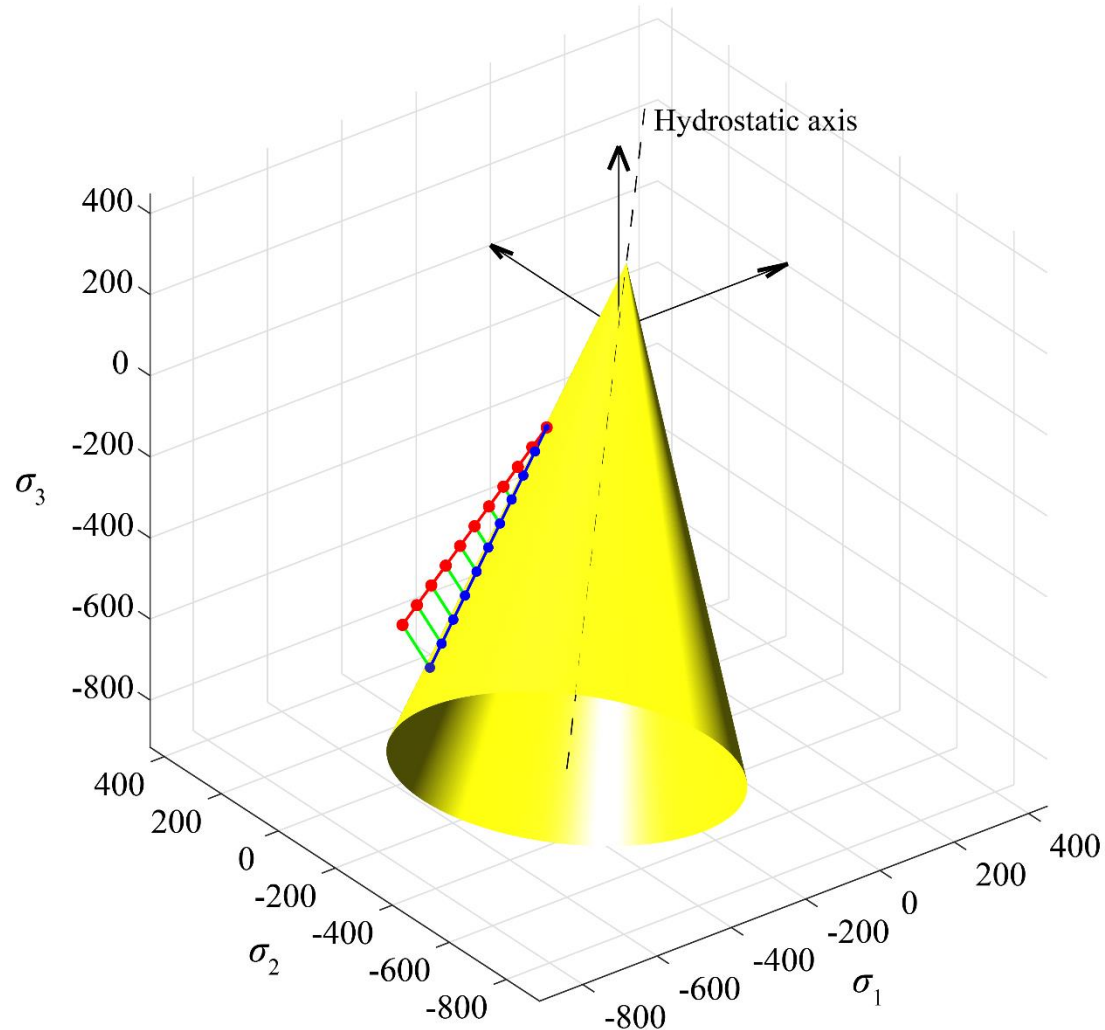
$$\phi_2(J_1(\boldsymbol{\varepsilon}), J_2(\boldsymbol{\varepsilon}_d)) = \frac{3\beta(1 + \nu)EJ_1(\boldsymbol{\varepsilon}) + (1 - 2\nu)[3E\sqrt{J_2(\boldsymbol{\varepsilon}_d)} - (3\beta + \sqrt{3})(1 + \nu)\sigma_y]}{E\{18\beta^2 E\sqrt{J_2(\boldsymbol{\varepsilon}_d)} - 3\beta[EJ_1(\boldsymbol{\varepsilon}) - (1 - 2\nu)\sigma_y] + \sqrt{3}(1 - 2\nu)\sigma_y\}}$$

Sonato M, Piccolroaz A, Miszuris W, Mishuris G. (2015). General transmission conditions for thin elasto-plastic pressure-dependent interphase between dissimilar materials. *Int J Solids Struct*, 64–65:9–21.

# Principal stress state of the nonlinear elastic model



# Projection of the trial inadmissible linear elastic stress state on the Drucker – Prager surface



# Analytical strain energy density function $\varphi$

## □ Explicit expression

**Key:** The increment of the stress components on the Drucker – Prager yield surface is constant with respect to the increment of the strain components.

$$\boldsymbol{\sigma} = \frac{\partial \varphi(J_1(\boldsymbol{\varepsilon}), J_2(\boldsymbol{\varepsilon}_d))}{\partial \boldsymbol{\varepsilon}}$$

$$\varphi = \frac{1}{2} \boldsymbol{\sigma}^I : \boldsymbol{\varepsilon}^I + (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}^I) \int_0^1 \boldsymbol{\sigma}' : \boldsymbol{\varepsilon}' dt$$

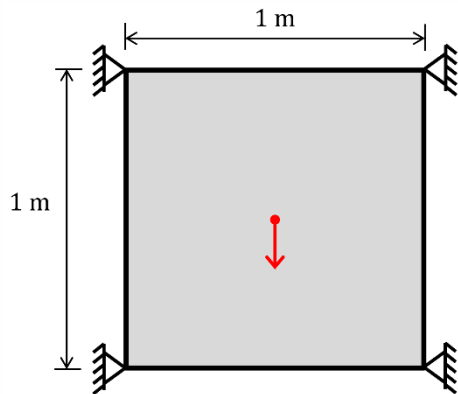
$$\boldsymbol{\varepsilon}' = (1 - t)\boldsymbol{\varepsilon}^I + t\boldsymbol{\varepsilon}$$

$$\boldsymbol{\sigma}' = (1 - t)\boldsymbol{\sigma}^I + t\boldsymbol{\sigma}$$

$$\varphi = \frac{1}{2} (\boldsymbol{\sigma}^I : \boldsymbol{\varepsilon} + \boldsymbol{\sigma} : \boldsymbol{\varepsilon} - \boldsymbol{\sigma} : \boldsymbol{\varepsilon}^I)$$

$$U(\boldsymbol{\rho}, \mathbf{u}(\boldsymbol{\rho})) = \sum_{e=1}^n \int_{V_e} \varphi_e(\mathbf{u}) dV$$

# Corner-supported square



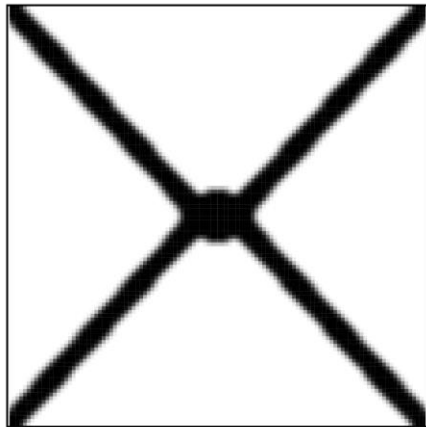
Young's modulus	$E = 1 \times 10^5 \text{ MPa}$
Poisson's ratio	$\nu = 0.3$
Tensile strength	$\sigma_t = 10 \text{ MPa}$ or $40 \text{ MPa}$
Compressive strength	$\sigma_c = 40 \text{ MPa}$

Symmetry: 6272 Q4 elements

Volume fraction:  $\bar{v} = 15\%$ ; Density filter radius:  $R = 0.018$

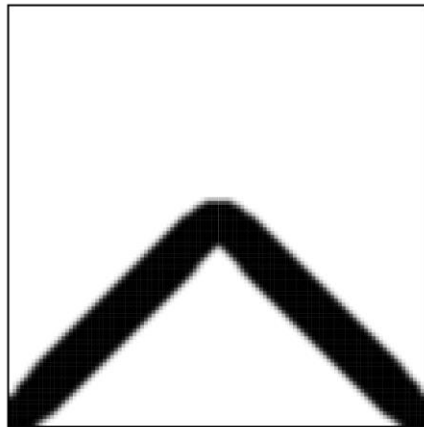
Constant penalty:  $p = 3$

$C_0 = 2 \times 10^{-6} \text{ MJ}$   
 $\sigma_t = 10 \text{ MPa}$      $\sigma_c = 40 \text{ MPa}$



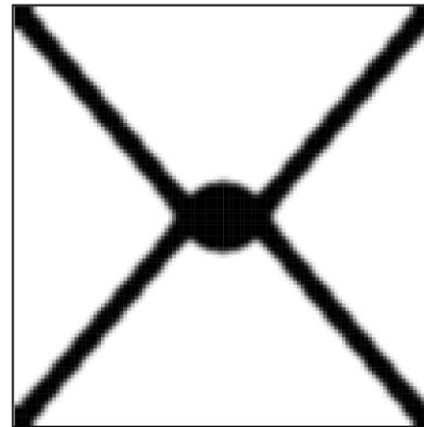
Linear solution

$C_0 = 2 \times 10^{-4} \text{ MJ}$   
 $\sigma_t = 10 \text{ MPa}$      $\sigma_c = 40 \text{ MPa}$



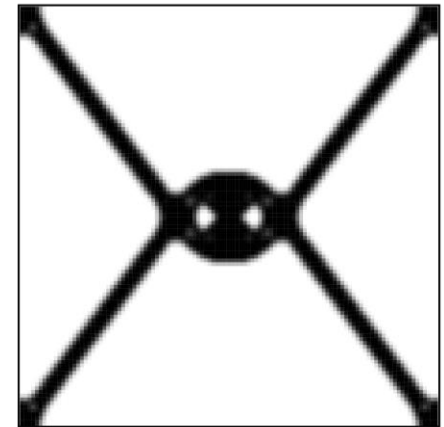
Nonlinear solution 1  
(Drucker-Prager)

$C_0 = 2 \times 10^{-4} \text{ MJ}$   
 $\sigma_t = 40 \text{ MPa}$      $\sigma_c = 40 \text{ MPa}$



Nonlinear solution 2  
(von Mises)

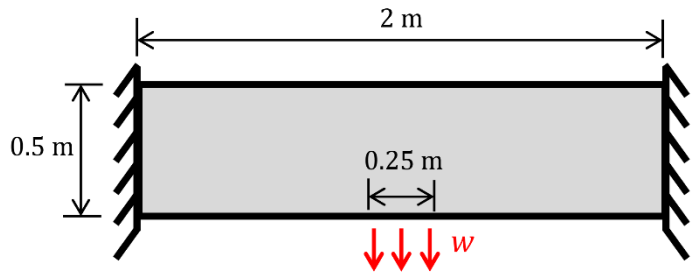
$C_0 = 2 \times 10^{-4} \text{ MJ}$   
 $\sigma_t = 10 \text{ MPa}$      $\sigma_c = 10 \text{ MPa}$



Nonlinear solution 3



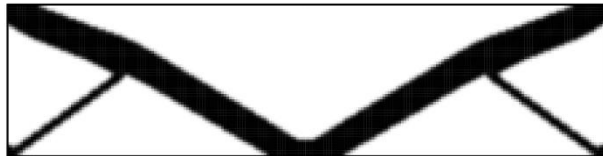
# Clamped beam



Young's modulus	$E = 1.8 \times 10^5 \text{ MPa}$
Poisson's ratio	$\nu = 0.3$
Tensile strength	$\sigma_t = 144 \text{ Mpa}$
Compressive strength	$\sigma_c = 1440 \text{ Mpa}$

Symmetry: 6272 Q4 elements  
Volume fraction:  $\bar{v} = 25\%$ ; Density filter radius:  $R = 0.014$   
Constant penalty:  $p = 3$

$$C_0 = 8 \times 10^{-4} \text{ MJ}$$



Linear solution

$$C_0 = 1.1 \times 10^{-2} \text{ MJ}$$



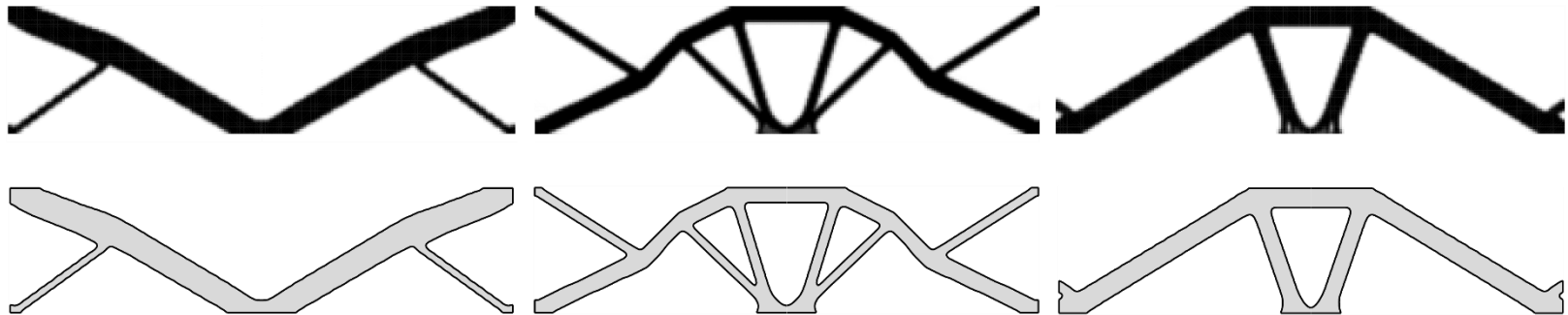
Nonlinear solution 1

$$C_0 = 1.3 \times 10^{-2} \text{ MJ}$$



Nonlinear solution 2

# Convert Optimized topologies to CAD models in ABAQUS



Volume = 0.2462

6145 linear triangular elements

Volume = 0.2466

6106 linear triangular elements

Volume = 0.2454

6171 linear triangular elements

## Material properties defined in ABAQUS:

Young's modulus  $E = 1.8 \times 10^5$  MPa

Poisson's ratio  $\nu = 0.3$

The Drucker – Prager plasticity model:

Friction angle  $\psi = 67.83^\circ$  and cohesion stress  $c = 261.82$  MPa

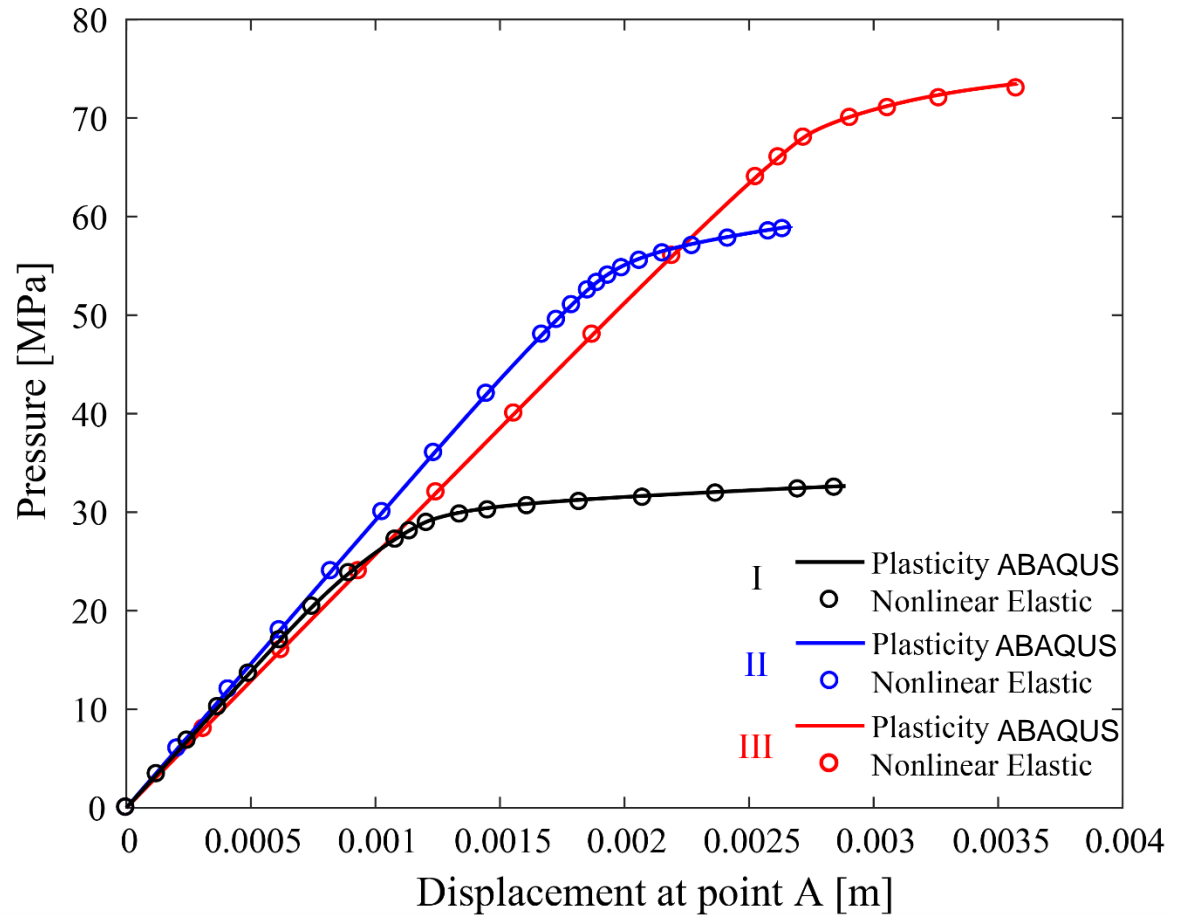
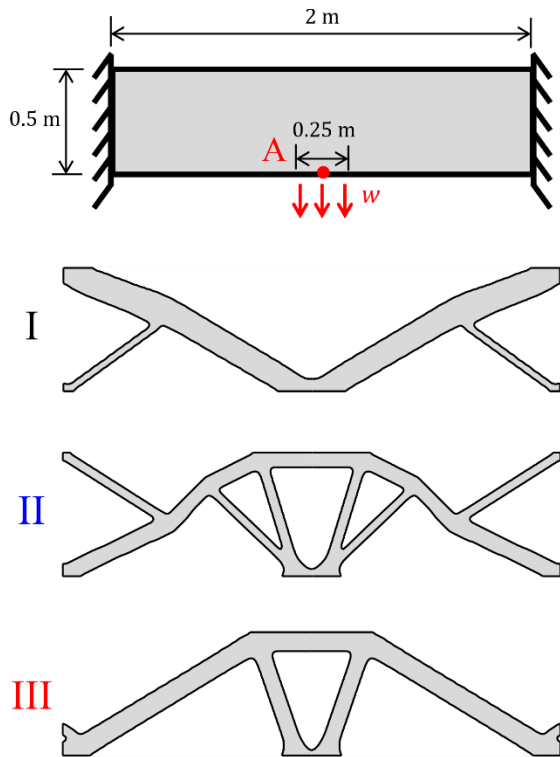
Standard ABAQUS

**OUR surrogate nonlinear elastic model (UMAT):**

$\nu^p = -0.175$  and  $\sigma_y = 144$  MPa

ABAQUS UMAT

# Structural performance



# Concluding remarks

- We address the material nonlinear topology optimization considering the Drucker – Prager criterion using a surrogate nonlinear elastic constitutive model.
- The sensitivity analysis are simple, effective and efficient for the present formulations (i.e.,  $\max U$  and  $\max \chi$ ).
- Using the analytical strain energy density function improves the efficiency of the framework.
- We obtain new nonlinear solutions accounting for realistic plastic material properties, which can serve as benchmark problems.
- Assuming small deformation, the nonlinear elastic solution is equivalent to the plastic solution under proportional loading.